

Time delay observable in classical and quantum geometries

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Outline

- 1 Motivation: Observables from Thought Experiments
- 2 Time Delay Observable and Classical Causality
- 3 Time Delay Observable in Quantum Linearized Gravity
- 4 Summary & Outlook

Motivation

If I had a theory of Quantum Gravity, what would I do with it?

- ▶ Answer should be independent of QG model.
- ▶ **My answer:** Compute qualitative and quantitative QG corrections to experiments and observations.
- ▶ Unfortunately, what is easiest to compute in QG is model dependent may not have a direct experimental interpretation.
- ▶ **Idea:** Work backwards! Start with a potential experiment (even if only in principle possible), described operationally. Construct a mathematical model of it and obtain an observable quantity with an unambiguous interpretation.
- ▶ **Bonus:** Direct comparison of various QG models.

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Observables from (Thought) Experiments

- ▶ Which experiments are sensitive to QG effects? All of them!
- ▶ However, we do not know which are most sensitive.
- ▶ A safe bet is to learn to model all experiments.
- ▶ Only when reliable methods for computing QG corrections are available, would it make sense to look for where the largest corrections occur.
- ▶ So, let's start with something easy!
... And see how it could lead to something interesting.

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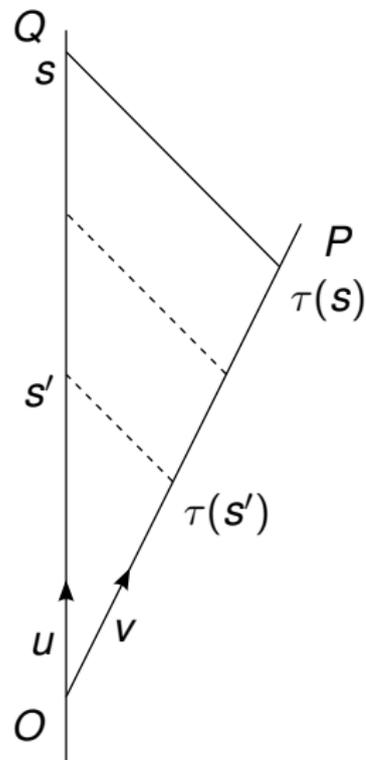
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Time Delay Observable

operational definition



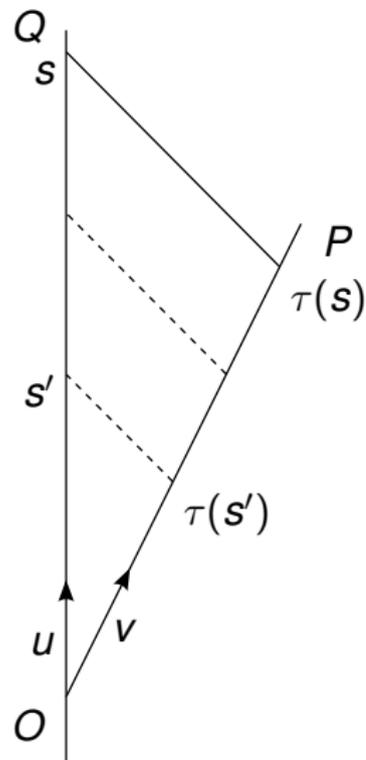
- ▶ Consider two inertially moving, localized systems: the **lab** and the **probe**. Probe is launched from the lab at event O .
- ▶ Each carries a **proper-time** clock. The clocks are synchronized at O .
- ▶ The probe broadcasts signals time stamped with the **emission time**, τ at P .
- ▶ The lab records the **reception time**, s at Q , together with the time stamp $\tau(s)$.
- ▶ The **time delay**

$$\delta\tau(s) = s - \tau(s)$$

is the observable we seek.

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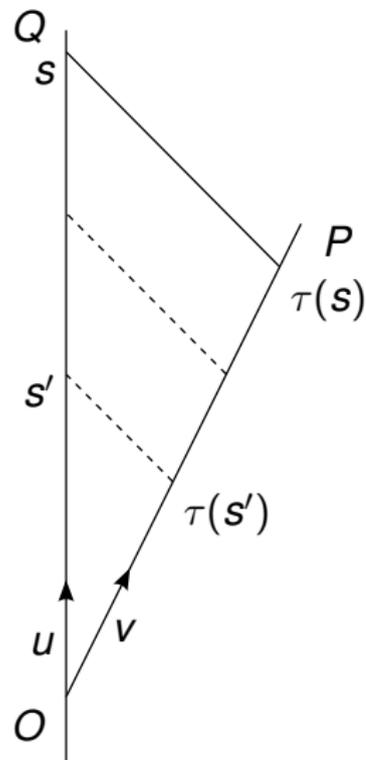
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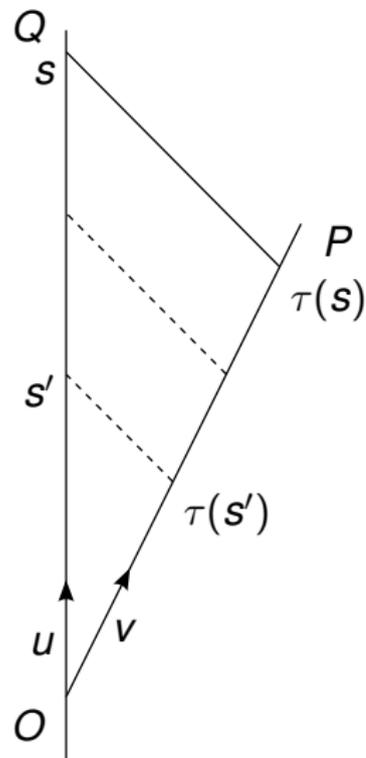
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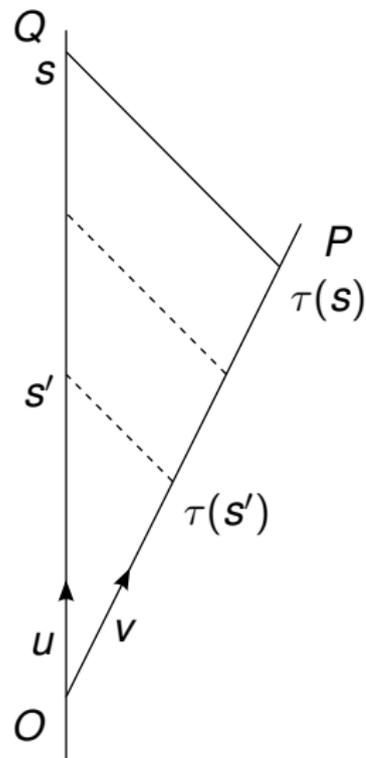
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Time Delay Observable

mathematical model

Definition (Spacetime + Apparatus)

A *lab-equipped spacetime* (M, g, O, e^α) is a (time oriented, globally hyperbolic) Lorentzian manifold (M, g) together with a point $O \in M$ and an orthonormal tetrad $e_i^\alpha \in T_O M$, with e_0^α timelike and future directed.

Definition (Gauge Equivalence)

Two *lab-equipped* spacetimes (M, g, O, e^α) and (M', g', O', e'^α) are *gauge equivalent* if there exists a diffeomorphism $\phi: M \rightarrow M'$ such that $\phi_* g = g'$, $\phi(O) = O'$ and $\phi_* e_i^\alpha = e'^\alpha_i$.

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Definition (Observers)

The *lab worldline* is the geodesic tangent to $u^\alpha = e_0^\alpha$ at O . The *probe worldline* is the geodesic tangent to $v^\alpha = v^i e_i^\alpha$ at O , for a timelike, unit, future directed $v^i \in \mathbb{R}^{1,3}$.

Definition (Signal)

For $t > 0$ and $V^\alpha = t v^\alpha$, let $P = \exp_O(V^\alpha)$ and let Q be the intersection of the lab worldline with $E^+(P)$ (future null cone of P).

Definition (Observables)

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Time Delay Observable

diffeomorphism invariance and causal bounds

Theorem (Gauge Invariance)

Given two *gauge equivalent, lab-equipped* spacetimes (M, g, O, e^α) and (M', g', O', e'^α) , the respective time delays $\delta\tau$ and $\delta\tau'$ (keeping s and v^i fixed) *are equal*.

Proof.

By construction. □

Remark:

- ▶ The time delay obeys interesting *inequalities*, which probe the *causal structure* of classical Lorentzian manifolds.

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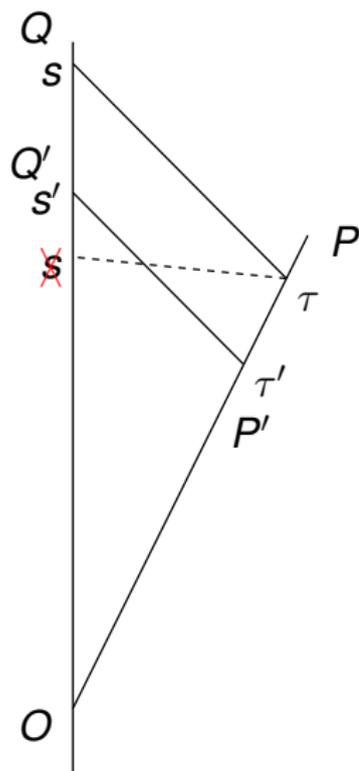
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causal bounds: speed of light



Theorem (Maximality of Light Speed)

In a Lorentzian geometry

$$\tau' < \tau \implies s' < s.$$

In particular, if $\tau(s)$ is smooth, then $\dot{\tau}(s) > 0$.

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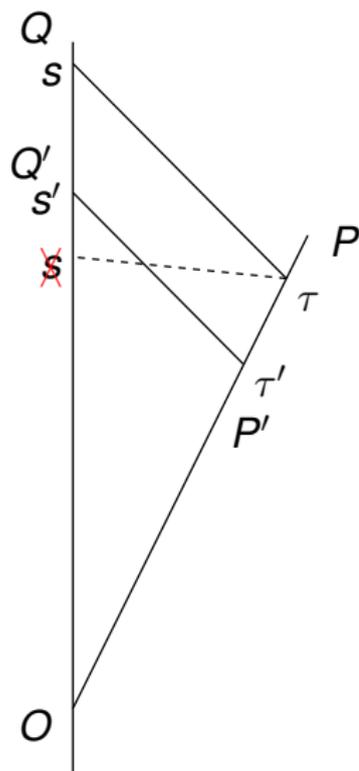
$$P \in I^+(P'), Q \in J^+(P) \implies Q \in \text{int} J^+(P').$$

[Hawking & Ellis, Proposition 4.5.10]

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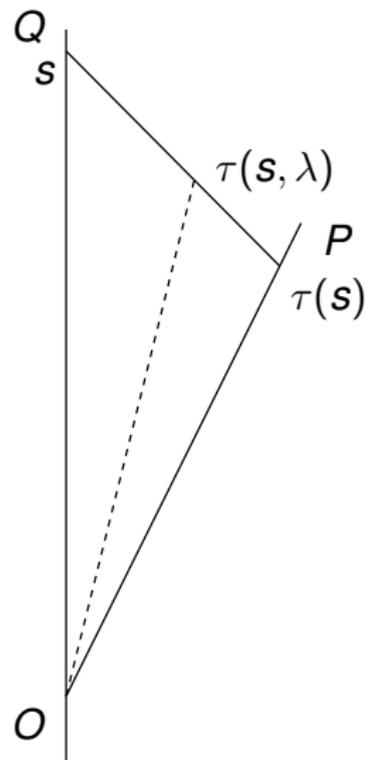
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Time Delay Observable

causal bounds: twin paradox



Theorem (Local Geodesic Extremality)
In a Lorentzian geometry

$$\tau(s) \leq s \quad (\text{or } \delta\tau(s) \geq 0).$$

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Adapt the formula for the **first variation** of the **length** of piecewise geodesics to show $\frac{\partial}{\partial\lambda}\tau(s, \lambda) < 0$ and write

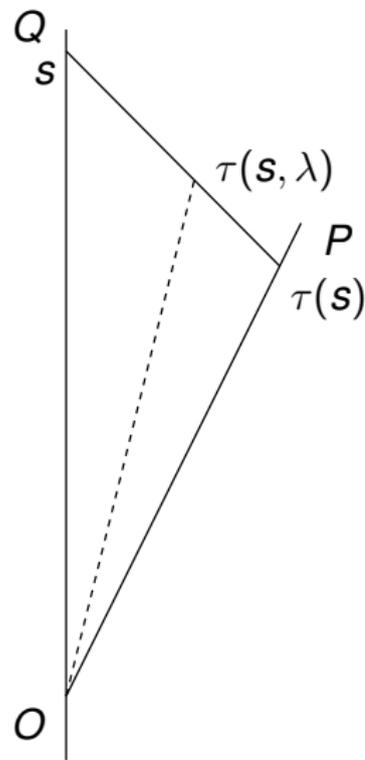
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Time Delay in Linearized Gravity

- ▶ **Linearization** about Minkowski space: $g_{\mu\nu} \rightarrow \eta_{\mu\nu} + h_{\mu\nu}$.
- ▶ **Explicit** expression for $\tau(s)$ at $O(h)$ is available:

$$\begin{aligned}\tau(s) &= \tau[\eta](s) + \tau_1[h](s) + \dots \\ &= se^{-\theta}(1 + r[h] + \dots) \\ r[h] &= r^x h_x = H + J\end{aligned}$$

- ▶ θ —rapidity, $v_{\text{rel}} = \tanh(\theta)$
 - ▶ r^x —integro-differential operator
 - ▶ H, J —separately **invariant** under linearized diffeomorphisms that fix O and e^α
- ▶ **Note:** H, J, \dots may have been found by brute force, but it would not have been obvious how these **invariants** would combine into an **observable** with direct **phenomenological interpretation**

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- ▶ **Quantum model** of experiment: add apparatus physical degrees freedom, take **limit** where irrelevant internal dynamics and **back reaction** on the geometry become **negligible**.
Use ideas of [Page & Wootters (1983)] and [Gambini & Pullin (2009)].
- ▶ **Time delay** observable: $\tau(s) \rightarrow \hat{\tau}(s) = se^{-\theta}(1 + r[\hat{h}] + \dots)$.
- ▶ The correction $r[\hat{h}]$ is **invariant** under linearized diffeomorphisms fixing O and e^α .
- ▶ Fock vacuum $|0\rangle$ is **invariant** under Poincaré transformations.
- ▶ Expectation values $\langle 0|F(r[\hat{h}]|0\rangle$ are **independent** of gauge and of choice of O and e^α .

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Causal Bounds in Quantum Linearized Gravity

Lorentzian signature

- ▶ For a **classical**, everywhere **small** h , $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$ is **Lorentzian**.
- ▶ For h **arbitrary**, $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$ may be **not Lorentzian**:
causal bounds **may not hold!**

- ▶ **Spectral Density** of **state** ψ with respect to **observable** \hat{A}

$$P_\psi(a) = \langle \psi | \delta(\hat{A} - a) | \psi \rangle$$

- ▶ \hat{A} —**observable**, operator on a Hilbert space
 - ▶ $|\psi\rangle$ —**state**, element of a Hilbert space
 - ▶ $\delta(\hat{A} - a)$ —**spectral projection**
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Lorentzian signature

- ▶ For a **classical**, everywhere **small** h , $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$ is **Lorentzian**.
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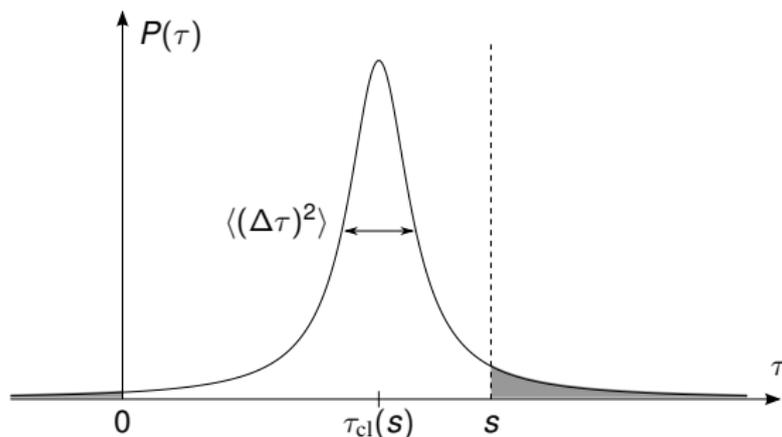
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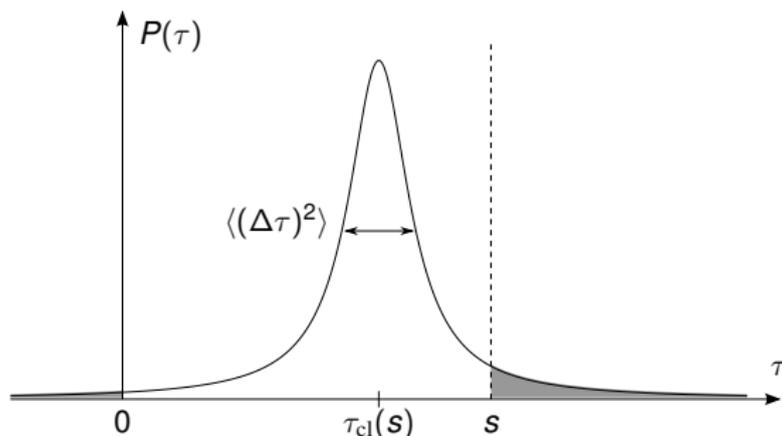
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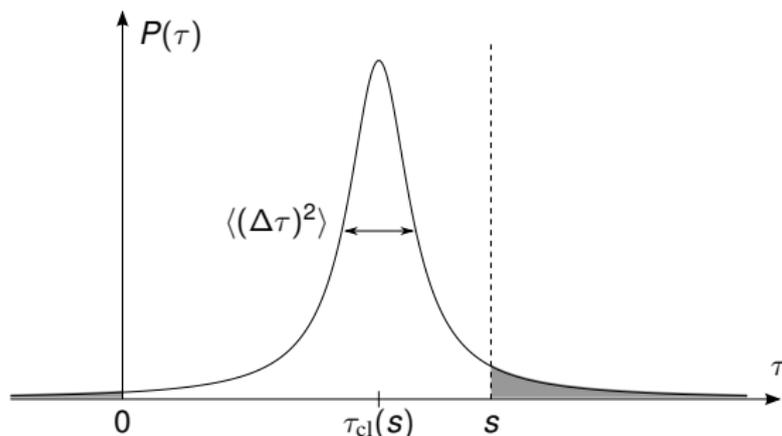
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Explicit Calculation

basic idea

- ▶ What to calculate?

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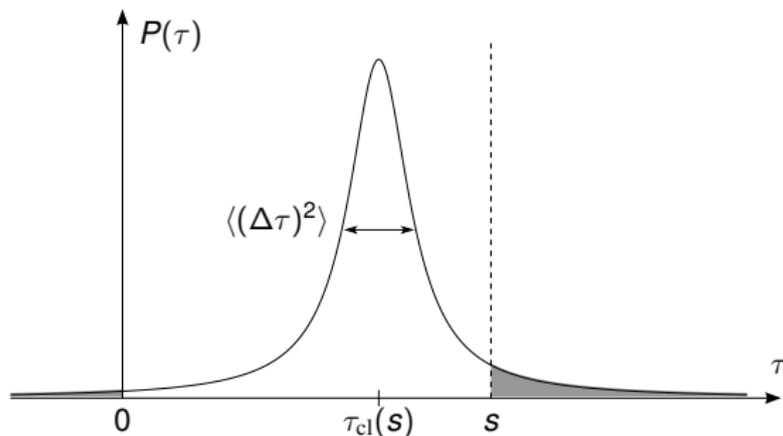
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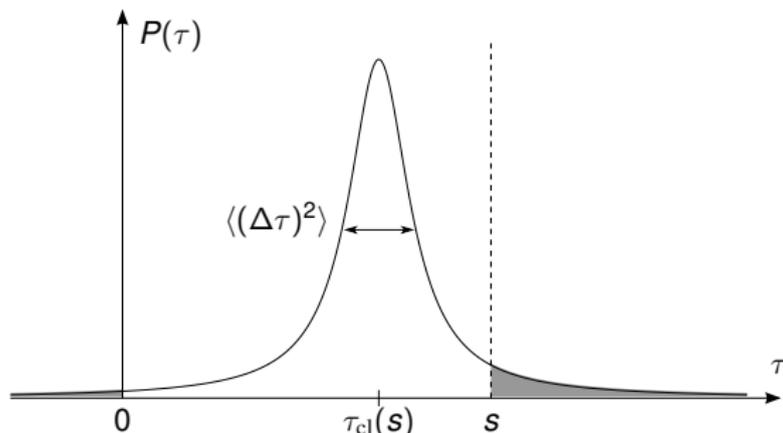
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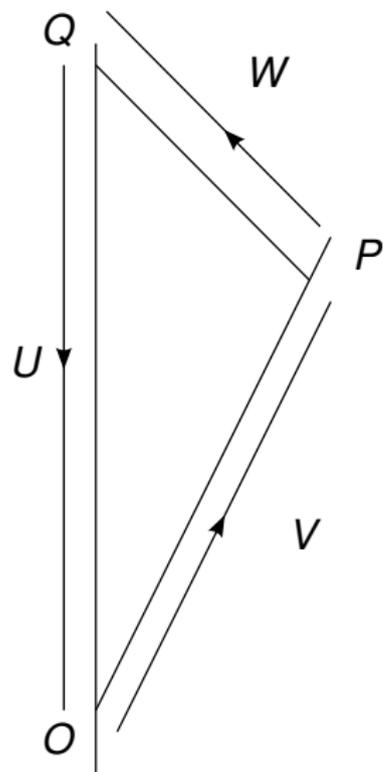
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Time Delay in Quantum Linearized Gravity

explicit expressions



$$r^x h_x = H + J$$

► **Explicit** expression:

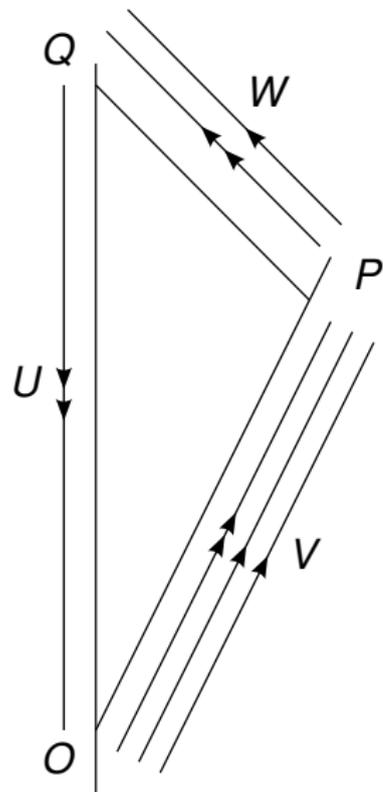
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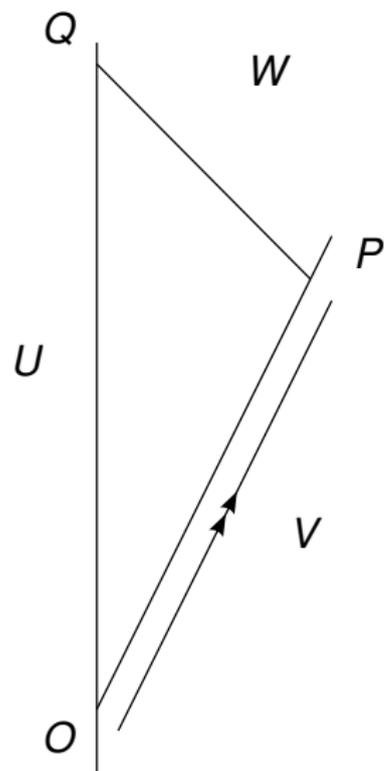
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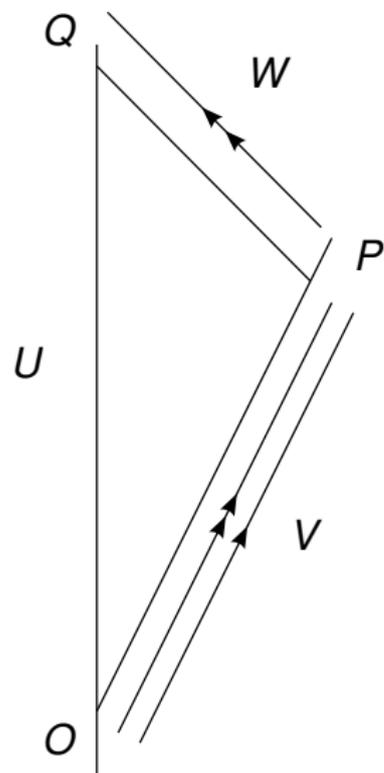
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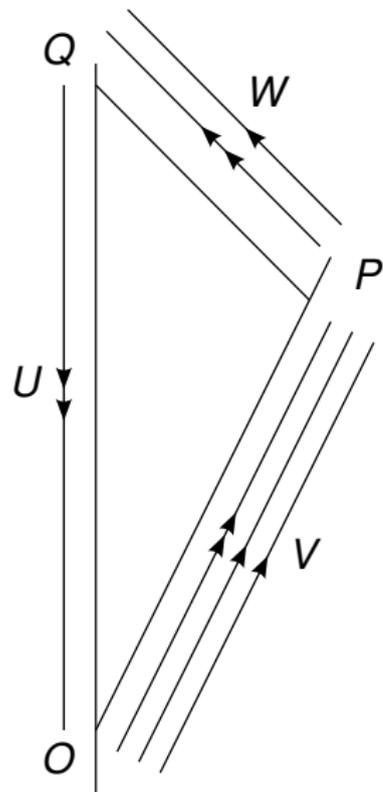
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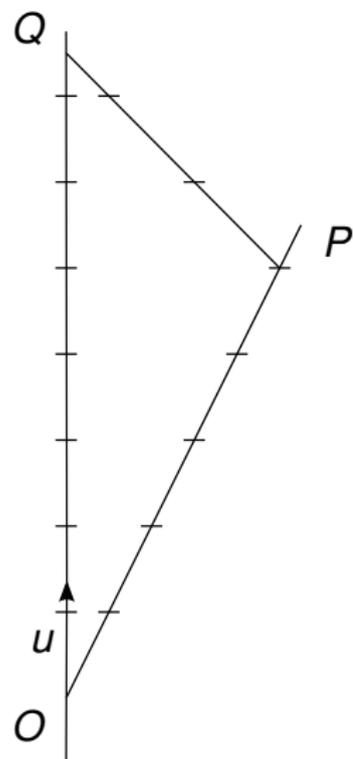
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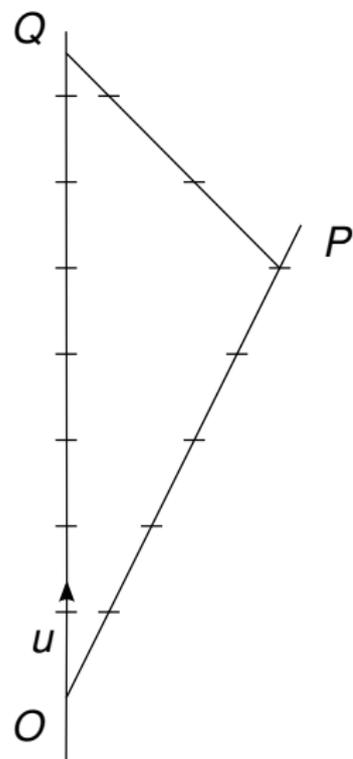
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Smearing and Detector Resolution



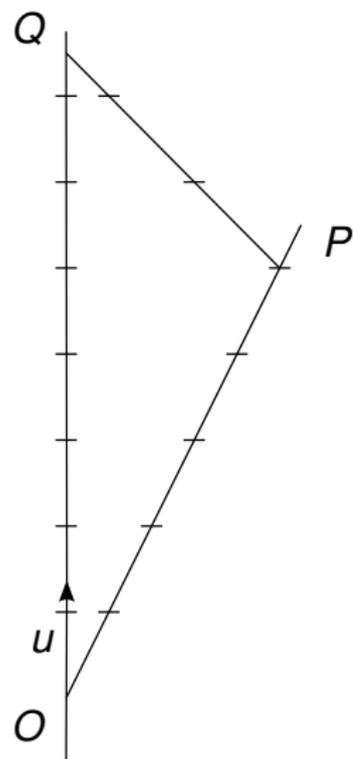
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- ▶ Physically speaking, μ , the spread of $\tilde{g}(x)$, is the **spatial resolution** of the detector.
- ▶ We can back-of-envelope **estimate** μ as the **wavelength** of the light/radio signals exchanged between lab and probe.
- ▶ A more detailed detector model should unambiguously fix $\tilde{g}(x)$ for each leg of $\triangle OPQ$.
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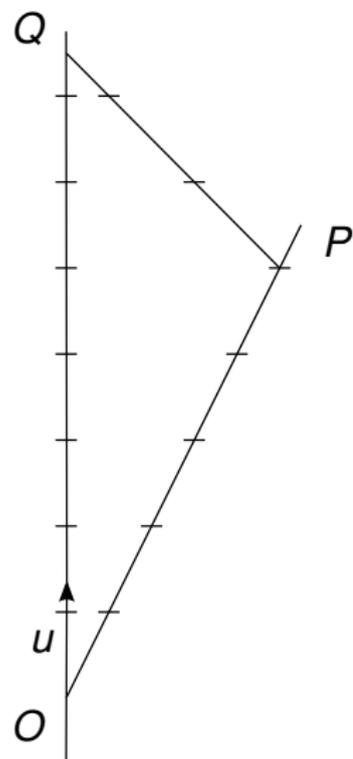
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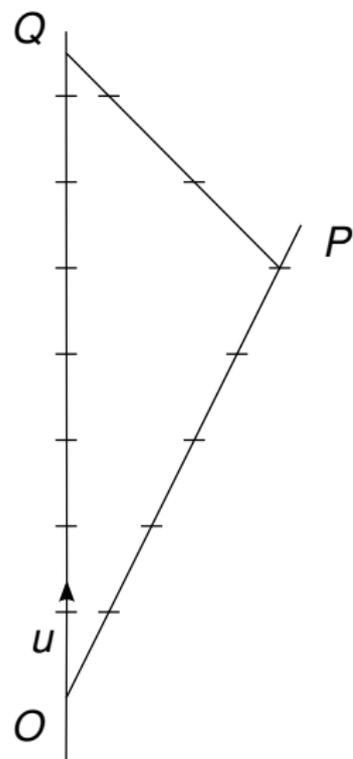
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computational strategy

- ▶ Start with $r^X = \sum_{|K| \leq mX} r_{mX}^K \int_X^{(m)} \nabla_K$ and conclude that

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dimensional analysis

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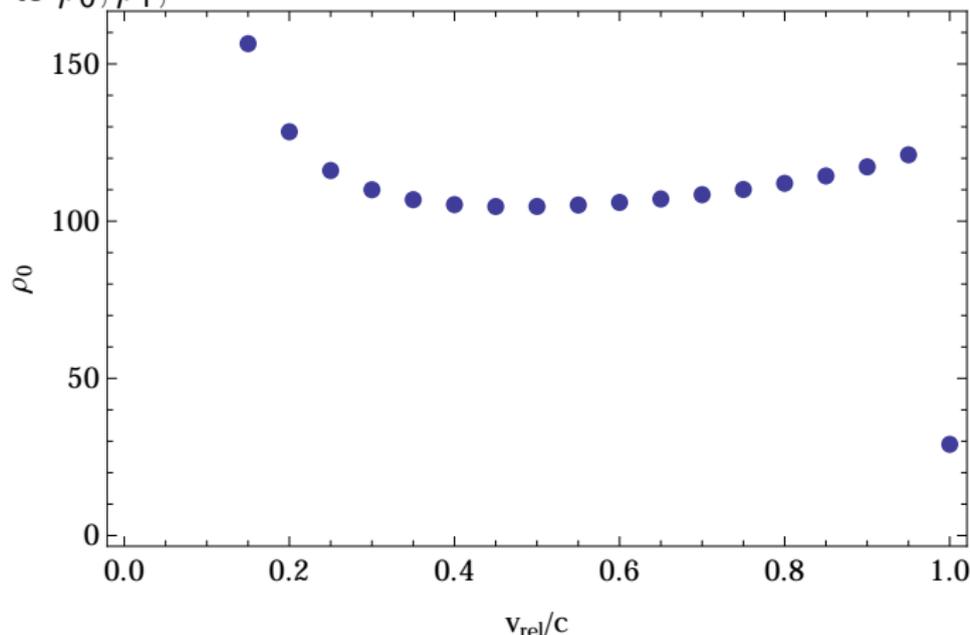
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Explicit Calculation

result [B. Bonga, MSc thesis]

All dependence on geometry (relative lab-probe speed v_{rel}/c) is in the coefficients ρ_0, ρ_1, \dots



The second coefficient is just $\rho_1 = -2\pi^2$.

Summary & Outlook

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Thank you for your attention!