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Type D Einstein spacetimes in higher dimensions

V Pravda¹, A Pravdová¹ and M Ortaggio^{2,3}

¹ Mathematical Institute, Academy of Sciences, Žitná 25, 115 67 Prague 1, Czech Republic
² Dipartimento di Fisica, Università degli Studi di Trento, and INFN, Gruppo Collegato di Trento, Via Sommarive 14, 38050 Povo (Trento), Italy

E-mail: pravda@math.cas.cz, pravdova@math.cas.cz and ortaggio@ffn.ub.es

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Abstract

We show that all *static* spacetimes in higher dimensions n > 4 are necessarily of Weyl types G, I_i, D or O. This also applies to *stationary* spacetimes provided additional conditions are fulfilled, as for most known black hole/ring solutions. (The conclusions change when the Killing generator becomes null, such as at Killing horizons, on which we briefly comment.) Next we demonstrate that the same Weyl types characterize warped product spacetimes with a onedimensional Lorentzian (timelike) factor, whereas warped spacetimes with a two-dimensional Lorentzian factor are restricted to the types D or O. By exploring algebraic consequences of the Bianchi identities, we then analyze the simplest non-trivial case from the above classes-type D vacuum spacetimes, possibly with a cosmological constant, dropping, however, the assumptions that the spacetime is static, stationary or warped. It is shown that for 'generic' type D vacuum spacetimes (as defined in the text) the corresponding principal null directions are *geodetic* in arbitrary dimension (this in fact also applies to type II spacetimes). For $n \ge 5$, however, there may exist particular cases of type D vacuum spacetimes which admit non-geodetic multiple principal null directions and we explicitly present such examples in any $n \ge 7$. Further studies are restricted to five dimensions, where the type D Weyl tensor is fully described by a 3 × 3 real matrix Φ_{ij} . In the case with 'twistfree' ($A_{ij} = 0$) principal null geodesics we show that in a 'generic' case Φ_{ij} is symmetric and eigenvectors of Φ_{ij} coincide with eigenvectors of the expansion matrix S_{ii} providing us thus in general with three preferred spacelike directions of the spacetime. Similar results are also obtained when relaxing the twistfree condition and assuming instead that Φ_{ij} is symmetric. The five-dimensional Myers-Perry black hole and Kerr-NUT-AdS metrics in arbitrary dimension are also briefly studied as specific illustrative examples of type D vacuum spacetimes.

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³ Now at Departament de Física Fonamental, Universitat de Barcelona, Diagonal 647, E-08028 Barcelona, Spain.

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1. Introduction

Algebraically special spacetimes play an essential role in the field of exact solutions of Einstein's equations and many known exact solutions in four dimensions are indeed algebraically special [1]. Recently, a generalization of the Petrov classification to higher dimensions was developed in [2, 3] and it turned out that many higher-dimensional solutions of Einstein's equations are algebraically special as well (see, e.g., [4]), in fact so far there is only one known solution identified [5] as algebraically general—the static charged black ring [6].

There is, however, one important difference between four-dimensional and n > 4 dimensional cases—the Goldberg–Sachs theorem does not hold in higher dimensions. Recall that for n = 4 the Goldberg–Sachs theorem implies that principal null directions of an algebraically special vacuum spacetime are necessarily geodetic and shearfree. It was stressed already in [7, 8] that the Goldberg–Sachs theorem cannot be straightforwardly extended to higher dimensions. Namely in [7] it was pointed out that principal null directions (or Weyl-aligned null directions (WANDs) [2]) of the n = 5 Myers–Perry black holes [9] are shearing though the spacetime is of type D. In [8] it was shown that in fact all vacuum, n > 4, type N and III expanding spacetimes are shearing. In [10] it was also shown that for n > 4, n odd, all geodetic WANDs with non-vanishing twist are again shearing.

In this paper, we study various properties of algebraically special vacuum spacetimes, such as geodeticity of multiple WANDs (not guaranteed in higher dimensions—another 'violation' of the Goldberg–Sachs theorem) and relationships between optical matrices S_{ij} and A_{ij} and the Weyl tensor. Before approaching these problems, we study in the first part of the paper (sections 3 and 4) constraints on Weyl types of the spacetime following from various assumptions on the geometry.

In section 3, we show that in arbitrary dimension⁴ the only Weyl types compatible with static spacetimes (and expanding stationary spacetimes with appropriate reflection symmetry) are types G, I_i , D and O.

In section 4, we study direct or warped product spacetimes. It turns out that warped spacetimes with a one-dimensional Lorentzian factor are again of types G, I_i , D and O and that warped spacetimes with a two-dimensional Lorentzian factor are necessarily of type D or O. This also implies that spherically symmetric spacetimes are of type D or O.

It follows that type D spacetimes play an important role as the simplest non-trivial case compatible with the aforementioned assumptions. Therefore, in the second part of the paper (sections 5 and 6) we focus on studying properties of type D Einstein spacetimes (i.e., vacuum with an arbitrary cosmological constant), dropping, however, the assumptions that the spacetime is static, stationary or warped.

In section 5, we study type D spacetimes in arbitrary dimension and analyze geodeticity of WANDs. It turns out that in a 'generic' case in vacuum the multiple WANDs are geodetic. Let us also point out that negative boost weight Weyl components do not enter relevant equations and thus the same results also hold for multiple WANDs in type II Einstein spacetimes. Surprisingly, it also turns out that explicit examples of special vacuum type D spacetimes not belonging to our 'generic' class and admitting non-geodetic multiple WANDs can easily be constructed. Such examples for arbitrary dimension $n \ge 7$ are given in section 5.4. This shows that there exist even more striking 'violations' of the Goldberg–Sachs theorem in higher dimensions than the examples with non-zero shear discussed above. In section 5, we also study various properties of shearfree type D vacuum spacetimes.

⁴ Note that for dimensions n < 4 the Weyl tensor vanishes and thus all statements about algebraical types are trivial. Consequently, throughout the paper by 'arbitrary dimension' we mean arbitrary $n \ge 4$.

Perhaps not surprisingly, the situation in five dimensions is considerably simpler than for n > 5. In fact, it turns out that for n = 5 the Weyl tensor of type D is fully determined by a 3×3 real matrix Φ_{ij} . At the same time, five-dimensional gravity is already an interesting arena where qualitatively new phenomena appear. We thus devote section 6 to five-dimensional vacuum type D spacetimes. We study relationships between the Weyl tensor represented by Φ_{ij} and optical matrices S_{ij} and A_{ij} . One of the results is that for 'generic' spacetimes with non-twisting WANDs ($A_{ij} = 0$) the antisymmetric part of Φ_{ij} , Φ_{ij}^A , vanishes and the symmetric part Φ_{ij}^S is aligned with S_{ij} (in the sense that the matrices Φ_{ij}^S and S_{ij} can be diagonalized together). Similarly, in the 'generic' case the condition $\Phi_{ij}^A = 0$ implies vanishing of A_{ij} . Again, there exist particular cases for which the 'generic' proof does not hold, see section 6 for details. In this section, a simple explicit example of a five-dimensional vacuum type D spacetime, the Myers–Perry metric, is also presented and S_{ij} , A_{ij} , Φ_{ij}^S , and Φ_{ij}^A are explicitly given.

Finally, in section 7 we concisely summarize the main results and in the appendix we briefly study the geometric optics of type D Kerr–NUT–AdS metrics in arbitrary dimension.

2. Preliminaries

Let us first briefly summarize our notation, further details can be found in [8]. In an *n*-dimensional spacetime let us introduce a frame of *n* real vectors $m^{(a)}(a, b, \ldots = 0, \ldots, n-1)$: two null vectors $m^{(0)} = m_{(1)} = n$, $m^{(1)} = m_{(0)} = \ell$ and n-2 orthonormal spacelike vectors $m^{(i)} = m_{(i)}$ $(i, j, \ldots = 2, \ldots, n-1)$ satisfying

$$\ell^a \ell_a = n^a n_a = \ell^a m_a^{(i)} = n^a m_a^{(i)} = 0, \qquad \ell^a n_a = 1, \qquad m^{(i)a} m_a^{(j)} = \delta_{ij}.$$
(1)

The metric now reads

$$g_{ab} = 2\ell_{(a}n_{b)} + \delta_{ij}m_{a}^{(i)}m_{b}^{(j)}.$$
(2)

We will use the following decomposition of the covariant derivative of the vector ℓ and the covariant derivative in the direction of ℓ :

$$\ell_{a;b} = L_{cd} m_a^{(c)} m_b^{(d)}, \qquad D \equiv \ell^a \nabla_a.$$
(3)

Note that ℓ is geodetic iff $L_{i0} = 0$ and for an affine parameterization also $L_{10} = 0$. We will often use the symmetric and antisymmetric parts of L_{ij} , $S_{ij} \equiv L_{(ij)}$ (its trace $S \equiv S_{ii}$), $A_{ij} \equiv L_{[ij]}$. In the case of geodetic ℓ , the trace of S_{ij} represents expansion $\theta \equiv \frac{1}{n-2}S$, the tracefree part of S_{ij} is shear $\sigma_{ij} \equiv S_{ij} - \theta \delta_{ij}$ and the antisymmetric matrix A_{ij} is twist⁵. Optical scalars can be expressed in terms of ℓ (when $L_{i0} = 0 = L_{10}$):

$$\sigma^{2} \equiv \sigma_{ij}\sigma_{ji} = \ell_{(a;b)}\ell^{(a;b)} - \frac{1}{n-2}\left(\ell^{a}_{;a}\right)^{2}, \quad \theta = \frac{1}{n-2}\ell^{a}_{;a}, \quad \omega^{2} \equiv A_{ij}A_{ij} = \ell_{[a;b]}\ell^{a;b}.$$
 (4)

The decomposition of the Weyl tensor in the frame (1) in full generality is given by [8]

$$\begin{split} C_{abcd} &= 4C_{0i0j}n_{\{a}m^{(i)}{}_{b}n_{c}m^{(j)}{}_{d\}} + 8C_{010i}n_{\{a}\ell_{b}n_{c}m^{(i)}{}_{d\}} + 4C_{0ijk}n_{\{a}m^{(i)}{}_{b}m^{(j)}{}_{c}m^{(k)}{}_{d\}} \\ &+ 4C_{0101}n_{\{a}\ell_{b}n_{c}\ell_{d\}} + 4C_{01ij}n_{\{a}\ell_{b}m^{(i)}{}_{c}m^{(j)}{}_{d\}} + 8C_{0i1j}n_{\{a}m^{(i)}{}_{b}\ell_{c}m^{(j)}{}_{d\}} \\ &+ C_{ijkl}m^{(i)}{}_{\{a}m^{(j)}{}_{b}m^{(k)}{}_{c}m^{(l)}{}_{d\}} + 8C_{101i}\ell_{\{a}n_{b}\ell_{c}m^{(j)}{}_{d\}} \\ &+ 4C_{1ijk}\ell_{\{a}m^{(i)}{}_{b}m^{(j)}{}_{c}m^{(k)}{}_{d\}} + 4C_{1i1j}\ell_{\{a}m^{(i)}{}_{b}\ell_{c}m^{(j)}{}_{b\}}, \end{split}$$

where the operation {} is defined as $w_{\{a}x_by_cz_d\} \equiv \frac{1}{2}(w_{[a}x_{b]}y_{[c}z_{d]} + w_{[c}x_{d]}y_{[a}z_{b]}).$

⁵ For the sake of brevity, throughout the paper we shall refer to the corresponding quantities for non-geodetic congruences as 'expansion', 'shear' and 'twist' (in inverted commas), keeping in mind that in that case expressions (4) do *not* hold.

In the second part of this paper we will focus on type D spacetimes, possessing (in an adapted frame) only boost order zero components (see [8]) C_{0101} , C_{01ij} , C_{0i1j} , C_{ijkl} . For simplicity, let us define the $(n - 2) \times (n - 2)$ real matrix

$$\Phi_{ij} \equiv C_{0i1j},\tag{5}$$

with Φ_{ij}^S , Φ_{ij}^A and $\Phi \equiv \Phi_{ii}$ being the symmetric and antisymmetric parts of Φ_{ij} and its trace, respectively. Let us observe that for static spacetimes and for a large class of warped geometries one has $\Phi_{ij}^A = 0$ (see section 4). Note also that the aforementioned boost order zero components of the Weyl tensor are not completely independent. In fact, from the symmetries and the tracelessness of the Weyl tensor (cf equations (7) and (9) in [8]) it follows that

$$C_{01ij} = 2C_{0[i|1|j]} = 2\Phi_{ij}^{A}, \qquad C_{0(i|1|j)} = \Phi_{ij}^{S} = -\frac{1}{2}C_{ikjk}, \qquad C_{0101} = -\frac{1}{2}C_{ijij} = \Phi.$$
(6)

The type D Weyl tensor is thus completely determined by $\frac{m(m-1)}{2}$ independent components of Φ_{ij}^A and $\frac{m^2(m^2-1)}{12}$ independent components of C_{ijkl} , where n = m - 2.6

3. Static and stationary spacetimes

3.1. Static spacetimes

Algebraically special spacetimes in higher dimensions are characterized by the existence of preferred null directions—Weyl-aligned null directions (WANDs). A necessary and sufficient condition for a null vector ℓ being WAND in arbitrary dimension is [3, 11]

$$\ell^b \ell^c \ell_{[e} C_{a]bc[d} \ell_{f]} = 0, \tag{7}$$

where C_{abcd} is the Weyl tensor. Let us now assume that a spacetime of interest is algebraically special and thus equation (7) possesses a null solution $\ell = (\ell^t, \ell^A), A = 1, ..., n - 1$ (note that necessarily $\ell^t \neq 0$ and at least one of the remaining components is also non-zero).

For static spacetimes the metric does not depend on the direction of time and consequently the form of the metric and the Weyl tensor remains unchanged under the transformation $\tilde{t} = -t$. Therefore, in these new coordinates equation (7) has the same form as in the original coordinates and admits a second solution $\tilde{n} = (\ell^t, \ell^A)$. In the original coordinates $n = (-\ell^t, \ell^A)$. Thus for static spacetimes the existence of a WAND ℓ implies the existence of a distinct WAND n which in fact has the same order of alignment. The only Weyl types compatible with this property are types G, I_i and D (or, trivially, O, i.e. conformally flat spacetimes). Therefore,

Proposition 1. All static spacetimes in arbitrary dimension are of Weyl types G, I_i or D, unless conformally flat.

In fact, explicit examples of static spacetimes of these Weyl types are known—charged static black ring (type G, [5]), vacuum static black ring (type I_i, [11]), the Schwarzschild–Tangherlini black hole (type D, [8]) and the Einstein universe $\mathbb{R} \times S^{n-1}$ (type O—compare with the results summarized in section 4). Also compare with the static examples given in [4].

Note that in four dimensions there is no type G and type I is equivalent to type I_i [2, 3]. Thus for n = 4 only types I, D and O are compatible with static spacetimes. This was discussed in [12] in the case of static, n = 4, vacuum spacetimes (see also additional comments in [13] and in section 6.2 of [1]).

⁶ In the standard n = 4 (i.e., m = 2) case these are essentially the imaginary and real parts of Ψ_2 . More specifically, with the conventions of [1], one has $\Phi_{ij}^S = \frac{1}{2} \Phi \delta_{ij}$ with $\Phi = -2\text{Re}(\Psi_2)$, $\Phi_{23}^A = \Phi_{23} = -\text{Im}(\Psi_2)$ as the only essential component of Φ_{ij}^A , while C_{ijkl} reduce to the only non-trivial component $C_{2323} = -\Phi$.

3.2. Stationary spacetimes

One can use the same arguments as above for stationary spacetimes with the metric remaining unchanged under reflection symmetry involving time and some other coordinates. For example, in Boyer-Lindquist coordinates the Kerr metric remains unchanged under $\tilde{t} = -t, \tilde{\phi} = -\phi$ and n = 5 Myers-Perry under $\tilde{t} = -t, \tilde{\phi} = -\phi, \tilde{\psi} = -\psi$ or, for a general dimension, Myers-Perry under $\tilde{t} = -t, \tilde{\phi}_i = -\phi_i$. Note, however, that in contrast to the static case, in some special stationary cases one could in principle get from the original WAND ℓ a 'new' WAND $n = -\ell$ which represents the same null direction. In order to deal with these special cases we note that the 'divergence scalar' (or, loosely speaking, 'expansion', since it does coincide with the standard expansion scalar in the case of geodetic, affinely parameterized null directions) of both WANDs n and ℓ related by reflection symmetry is the same (as well as all the other optical scalars and the geodeticity parameters—this also applies to the static case), i.e. $\ell^a_{;a} = n^a_{;a}$ while the 'expansion' of $-\ell$ is equal to $-\ell^a_{;a}$. Therefore, for all 'expanding' spacetimes $n \neq -\ell$. Thus,

Proposition 2. In arbitrary dimension, all stationary spacetimes with non-vanishing divergence scalar ('expansion') and invariant under appropriate reflection symmetry are of Weyl types G, I_i or D, unless conformally flat.

Note also that it is shown in [14] that Kerr–Schild spacetimes with the assumption $R_{00} = 0$ are of type II (or more special) in arbitrary dimension with the Kerr–Schild vector being the multiple WAND. Therefore, all Kerr–Schild spacetimes that are either static or belong to the aforementioned class of stationary spacetimes are necessarily of type D. In particular, *the Myers–Perry metric in arbitrary dimension is thus of type D*.⁷

In addition to the rotating Myers–Perry black holes for $n \ge 4$, of type D, we can mention a number of physically relevant solutions as explicit examples of spacetimes subject to proposition 2.⁸ First, rotating vacuum black rings [17], of type I_i [11]. To our knowledge, no stationary (non-static) type G solution has been so far explicitly identified. It is, however, plausible to expect that a rotating charged black ring (so far unknown in the standard Einstein–Maxwell theory) will be of type G as its static counterparts. Further interesting examples fulfilling our assumptions are expanding stationary axisymmetric spacetimes with n - 2 commuting Killing vector fields [18], which also contain, apart from the (n = 5)black holes/rings mentioned above, e.g. the recently obtained 'black saturn' [19], doubly spinning black rings [20] and black di-rings [21]. In any dimension rotating uniform black strings/branes also satisfy the assumptions of proposition 2 (see section 4), and so does the ansatz recently used in [22] for the numerical construction of corresponding n = 6 nonuniform solutions. Other examples are all the stationary solutions discussed in [4] and the various black ring solutions reviewed in [23].

⁷ This was already known in the case n = 5 [8, 4]. Furthermore, it has been demonstrated recently in [15] by explicit computation of the full curvature tensor that the family [16] of higher-dimensional rotating black holes with a cosmological constant and NUT parameter is of type D for any *n*. We observe in addition that, using the connection 1-forms given in [15], it is also straightforward to show (see the appendix) that the multiple WANDs (which are related by reflection symmetry) of all such solutions are twisting, expanding and shearing (except that the shear vanishes for n = 4). The fact that the WANDs found in [15] are *complex* is only due to the analytical continuation trick used in [16] to cast the line element in a nicely symmetric form—the WANDs of the associated 'physical' spacetimes are thus *real* after Wick-rotating back one of the coordinates.

⁸ It is straightforward to verify the 'reflexion symmetry' of the metric we mention in this context. The 'expansion' condition, instead, has not been verified explicitly in all cases. However, it is plausible that these spacetimes are indeed 'expanding' since they contain as special limits or subcases solutions with expansion, e.g. Myers–Perry black holes (cf section 6.4, [8] and the preceding footnote).

3.3. Remarks and 'limitations' of the results

First, it is worth observing that we have not used any field equations for the gravitational field in the considerations presented above and the results are thus purely geometrical.

Note that one cannot relax the assumption $\ell^a{}_{;a} \neq 0$ in the case of stationary spacetimes. For example, the special pp-wave metric $ds^2 = g_{ij} dx^i dx^j - 2 du dv - 2H du^2$ such that $H_{,u} = 0$ (note that it is always $H_{,v} = 0$ by the definition of pp-waves) and $\partial_u \cdot \partial_u = -2H < 0$ represents stationary spacetimes (cf, e.g., [24] for the n = 4 vacuum case) that are invariant under reflection symmetry ($\tilde{u} = -u, \tilde{v} = -v$) and yet of type N [25]. In fact, the geodetic multiple WAND $\ell = \partial_v$ is non-expanding (and $n = -\ell$ is not a new WAND).

Furthermore, if we assume a *null Killing vector field* k instead of a timelike one we are led to different conclusions. Namely, it is easy to show that k must be geodetic, shearfree and non-expanding, which for $R_{ab}k^ak^b = 0$ implies that k is a twistfree WAND [10]. We thus end up with a subfamily of the Kundt class, for which (under the alignment requirement $R_{ab}k^a \propto k_b$, obeyed, e.g., in vacuum) the algebraic type is II or more special [10] (cf section 24.4 of [1] for n = 4). In particular, a similar argument applies locally at Killing horizons, where the type must thus again be II or more special (provided $R_{ab}k^a \propto k_b$).⁹ This is in agreement with the result of [26] for generic isolated horizons. As an explicit example, vacuum black rings (which are of type I_i in the stationary region) become locally of type II on the horizon [11].

Finally, spacelike Killing vectors do not impose any constraint on the algebraic type of the Weyl tensor, in general, and all types are in fact possible. For example, charged static black rings are of type G, vacuum black rings of type I_i , vacuum black holes of type D, and they all admit at least one spacelike Killing vector; Kundt spacetimes can be constructed that admit axial symmetry with all types II, D, III and N being possible (see, e.g., [1] for n = 4).

4. Direct/warped product spacetimes

In this section, we show that the algebraic types discussed above also characterize certain classes of direct/warped product geometries of physical relevance. In addition, we discuss some optical properties of these spacetimes.

4.1. Weyl tensor

Let us consider two (pseudo-)Riemannian spaces $(M_1, g_{(1)})$ and $(M_2, g_{(2)})$ of dimension n_1 and $n_2 (n_1, n_2 \ge 1$ and $n_1 + n_2 \ge 4$), parameterized by coordinates $x^A (A, B = 0, ..., n_1 - 1)$ and $x^I (I, J = n_1, ..., n_1 + n_2 - 1)$, respectively. Using adapted coordinates x^{μ} $(\mu, \nu = 0, ..., n_1 + n_2 - 1)$ constructed from the coordinates x^A of M_1 and x^I of M_2 , we define the *direct product* (M, g) to be the product manifold $M = M_1 \times M_2$, of dimension $n = n_1 + n_2$, equipped with the metric tensor $g(x^{\mu}) = g_{(1)}(x^A) \oplus g_{(2)}(x^I)$ defined (locally) by $g_{AB} = g_{(1)AB}, g_{IJ} = g_{(2)IJ}, g_{AI} = 0$. For the sake of definiteness, we shall assume hereafter that (M_1, g_1) is Lorentzian and (M_2, g_2) is Riemannian.

In general, any geometric quantity which can be split like the product metric (i.e., with no mixed components and with the A[I] components depending only on the $x^A[x^I]$ coordinates) is called a 'product object' (or 'decomposable'). Various interesting geometrical properties then follow [28] and, in particular, the Riemann and Ricci tensors and the Ricci scalar are all decomposable. As a consequence, *a product space is an Einstein space iff each factor is an Einstein space and their Ricci scalars satisfy* $R_{(1)}/n_1 = R_{(2)}/n_2$ [28].

⁹ The proof is a bit more tricky in this case since the Killing vector is null only at the horizon. Still, one can adapt techniques used in [26, 27] for related investigations. Note that the horizon of higher-dimensional stationary black holes is indeed a Killing horizon (at least in the non-degenerate case) [27].

Using the above coordinates it follows from the standard definition that the mixed components of the Weyl tensor are given by

$$C_{ABCI} = C_{ABIJ} = C_{AIJK} = 0,$$

$$C_{AIBJ} = -\frac{1}{n-2}(g_{(1)AB}R_{(2)IJ} + g_{(2)IJ}R_{(1)AB}) + \frac{R_{(1)} + R_{(2)}}{(n-1)(n-2)}g_{(1)AB}g_{(2)IJ},$$
(9)

where $R_{(1)AB}$ [$R_{(2)IJ}$] is the Ricci tensor of (M_1, g_1) [(M_2, g_2)]. For the non-mixed components one has to distinguish the special cases $n_1 = 1, 2$ (and the 'symmetric' cases $n_2 = 1, 2$, which we omit for brevity). If $n_1 = 1$ there are of course no non-mixed components C_{ABCD} since now x^A span a one-dimensional space. If $n_1 = 2$ there is only one independent component, i.e. C_{0101} (note that here, exceptionally, 0 and 1 are not frame indices but refer to the coordinates x^0 and x^1 in the factor space M_1). For $n_1 \ge 3$,

$$C_{ABCD} = C_{(1)ABCD} + \frac{2n_2}{(n-2)(n_1-2)} (g_{(1)A[C}R_{(1)D]B} - g_{(1)B[C}R_{(1)D]A}) + \frac{2}{(n-1)(n-2)} \left[R_{(2)} - R_{(1)} \frac{n_2(n_2+2n_1-3)}{(n_1-1)(n_1-2)} \right] g_{(1)A[C}g_{(1)D]B} \qquad (n_1 \ge 3),$$
(10)

where $C_{(1)ABCD}$ is the Weyl tensor of (M_1, g_1) , whereas the remaining non-mixed components are given for any $n_1 \ge 1$ by

$$C_{IJKL} = C_{(2)IJKL} + \frac{2n_1}{(n-2)(n_2-2)} (g_{(2)I[K} R_{(2)L]J} - g_{(2)J[K} R_{(2)L]I}) + \frac{2}{(n-1)(n-2)} \left[R_{(1)} - R_{(2)} \frac{n_1(n_1+2n_2-3)}{(n_2-1)(n_2-2)} \right] g_{(2)I[K} g_{(2)L]J} \qquad (n_2 \ge 3),$$
(11)

where $C_{(2)IJKL}$ is the Weyl tensor of (M_2, g_2) . It is thus obvious that the Weyl tensor is not decomposable, in general. It turns out that *the Weyl tensor is decomposable iff both product spaces are Einstein spaces and* $n_2(n_2 - 1)R_{(1)} + n_1(n_1 - 1)R_{(2)} = 0$ (the latter condition is identically satisfied whenever $n_1 = 1$ or $n_2 = 1$, while for $n_1 = 2$ [$n_2 = 2$] it implies that (M_1, g_1) [(M_2, g_2)] must be of constant curvature). When the Weyl tensor is decomposable the only non-vanishing components take the simple form $C_{ABCD} = C_{(1)ABCD}$, $C_{IJKL} = C_{(2)IJKL}$. Therefore, in particular, the product space is conformally flat iff both product spaces are of constant curvature and $n_2(n_2 - 1)R_{(1)} + n_1(n_1 - 1)R_{(2)} = 0$.

Determining the possible algebraic types of the Weyl tensor requires considering various possible choices for the dimension n_1 of the Lorentzian factor.

If $n_1 = 1$, the full metric can always be cast in the special static form $ds^2 = -dt^2 + g_{IJ} dx^I dx^J$. Recalling the result of section 3, the Weyl tensor can thus only be of type G, I_i, D or O. In particular, one can show that $C_{0i1j} = C_{0j1i}$, so that for direct product spacetimes with $n_1 = 1$ one has $\Phi_{ij}^A = 0$ identically.

If $n_1 \ge 2$, it is convenient to adapt the null frame (1) to the natural product structure, so that $g_{ab} = 2\ell_{(a}n_{b)} + \delta_{\hat{A}\hat{B}}m_a^{(\hat{A})}m_b^{(\hat{B})} + \delta_{\hat{I}\hat{J}}m_a^{(\hat{I})}m_b^{(\hat{J})}$ (where $\hat{A}, \hat{B} = 2, ..., n_1 - 1, \hat{I}, \hat{J} = n_1, ..., n - 1$ are now frame indices, and the frame vectors do not have mixed coordinate components, e.g., $\ell^I = 0 = n^I$, etc). From (10) and (11) it thus follows that C_{ABCD} and C_{IJKL} do not give rise to mixed frame components, and from (9) that C_{AIBJ} does not give rise to non-mixed frame components. Hence, the only non-vanishing mixed components are (ordered by boost weight)

$$C_{0\hat{f}0\hat{j}} = -\frac{1}{n-2} R_{(1)00} \delta_{\hat{f}\hat{j}}, \qquad C_{0\hat{f}\hat{A}\hat{f}} = -\frac{1}{n-2} R_{(1)0\hat{A}} \delta_{\hat{f}\hat{f}}, C_{0\hat{f}1\hat{f}} = -\frac{1}{n-2} (R_{(2)\hat{f}\hat{f}} + R_{(1)01} \delta_{\hat{f}\hat{f}}) + \frac{R_{(1)} + R_{(2)}}{(n-1)(n-2)} \delta_{\hat{f}\hat{f}}, C_{\hat{A}\hat{f}\hat{B}\hat{f}} = -\frac{1}{n-2} (R_{(2)\hat{f}\hat{f}} \delta_{\hat{A}\hat{B}} + R_{(1)\hat{A}\hat{B}} \delta_{\hat{f}\hat{f}}) + \frac{R_{(1)} + R_{(2)}}{(n-1)(n-2)} \delta_{\hat{A}\hat{B}} \delta_{\hat{f}\hat{f}}, C_{1\hat{f}\hat{A}\hat{f}} = -\frac{1}{n-2} R_{(1)1\hat{A}} \delta_{\hat{f}\hat{f}}, \qquad C_{1\hat{f}1\hat{f}} = -\frac{1}{n-2} R_{(1)11} \delta_{\hat{f}\hat{f}}.$$

$$(12)$$

The non-mixed frame components are given for $n_1 = 2$ by

$$C_{0101} = -\frac{1}{2(n_2 + 1)} \left[(n_2 - 1)R_{(1)} + \frac{2R_{(2)}}{n_2} \right] \qquad (n_1 = 2), \tag{13}$$

and for $n_1 \ge 3$ by

$$\begin{split} C_{0\hat{A}0\hat{B}} &= C_{(1)0\hat{A}0\hat{B}} + \frac{n_2}{(n-2)(n_1-2)} R_{(1)00} \delta_{\hat{A}\hat{B}}, \\ C_{010\hat{A}} &= C_{(1)010\hat{A}} - \frac{n_2}{(n-2)(n_1-2)} R_{(1)0\hat{A}}, \\ C_{0\hat{A}\hat{B}\hat{C}} &= C_{(1)0\hat{A}\hat{B}\hat{C}} - \frac{2n_2}{(n-2)(n_1-2)} R_{(1)0\hat{C}} \delta_{\hat{B}\hat{I}\hat{A}}, \\ C_{0101} &= C_{(1)0101} - \frac{2n_2}{(n-2)(n_1-2)} R_{(1)01} \\ &\qquad - \frac{1}{(n-1)(n-2)} \left[R_{(2)} - R_{(1)} \frac{n_2(n_2+2n_1-3)}{(n_1-1)(n_1-2)} \right], \\ C_{01\hat{A}\hat{B}} &= C_{(1)01\hat{A}\hat{B}} \end{split}$$
 $(n_1 \ge 3),$

$$C_{0\hat{A}1\hat{B}} = C_{(1)0\hat{A}1\hat{B}} + \frac{n_2}{(n-2)(n_1-2)} (R_{(1)\hat{A}\hat{B}} + R_{(1)01}\delta_{\hat{A}\hat{B}}) + \frac{1}{(n-1)(n-2)} \left[R_{(2)} - R_{(1)}\frac{n_2(n_2+2n_1-3)}{(n_1-1)(n_1-2)} \right] \delta_{\hat{A}\hat{B}},$$
(14)
$$C_{\hat{A}\hat{B}\hat{C}\hat{D}} = C_{(1)\hat{A}\hat{B}\hat{C}\hat{D}} + \frac{2n_2}{(n-2)(n_1-2)} (R_{(1)\hat{B}[\hat{D}}\delta_{\hat{C}]\hat{A}} - R_{(1)\hat{A}[\hat{D}}\delta_{\hat{C}]\hat{B}})$$

$$\begin{split} &+ \frac{2}{(n-1)(n-2)} \left[R_{(2)} - R_{(1)} \frac{n_2(n_2 + 2n_1 - 3)}{(n_1 - 1)(n_1 - 2)} \right] \delta_{\hat{B}[\hat{D}} \delta_{\hat{C}]\hat{A}}, \\ C_{\hat{I}\hat{J}\hat{K}\hat{L}} &= C_{(2)\hat{I}\hat{J}\hat{K}\hat{L}} + \frac{2n_1}{(n-2)(n_2 - 2)} (\delta_{\hat{I}[\hat{K}} R_{(2)\hat{L}]\hat{J}} - \delta_{\hat{J}[\hat{K}} R_{(2)\hat{L}]\hat{I}}) \\ &+ \frac{2}{(n-1)(n-2)} \left[R_{(1)} - R_{(2)} \frac{n_1(n_1 + 2n_2 - 3)}{(n_2 - 1)(n_2 - 2)} \right] \delta_{\hat{I}[\hat{K}} \delta_{\hat{L}]\hat{J}}, \\ C_{1\hat{A}\hat{B}\hat{C}} &= C_{(1)1\hat{A}\hat{B}\hat{C}} - \frac{2n_2}{(n-2)(n_1 - 2)} R_{(1)1[\hat{C}} \delta_{\hat{B}]\hat{A}}, \\ C_{101\hat{A}} &= C_{(1)101\hat{A}} - \frac{n_2}{(n-2)(n_1 - 2)} R_{(1)11\hat{A}}, \\ C_{1\hat{A}1\hat{B}} &= C_{(1)1\hat{A}1\hat{B}} + \frac{n_2}{(n-2)(n_1 - 2)} R_{(1)11} \delta_{\hat{A}\hat{B}}. \end{split}$$

(The expression for $C_{\hat{I}\hat{J}\hat{K}\hat{L}}$ holds only when $n_2 \ge 3$, while for $n_2 = 2$ one gets only one component C_{2323} similar to (13).)

For $n_1 = 2$, the Weyl tensor of (M_1, g_1) of course vanishes, and in addition we have $R_{(1)00} = 0 = R_{(1)11}$ identically (any 2-space satisfies $2R_{(1)AB} = R_{(1)}g_{(1)AB}$). Therefore, among the above components (12) and (13) only the boost weight zero components $C_{0\hat{1}1\hat{j}}$ and C_{0101} survive, so that the corresponding spacetime can be only of type D (or conformally flat), and ℓ and n, as chosen above, are multiple WANDs. Note also that Φ_{ij} reduces to $\Phi_{\hat{i}\hat{j}} = C_{0\hat{j}1\hat{j}} = C_{0\hat{j}1\hat{j}}$ in this case, therefore $\Phi_{ij}^A = 0$. As an example, the higher-dimensional electric Bertotti–Robinson solutions fall in this class, cf, e.g., [29, 30].

For $n_1 = 3$, again the Weyl tensor of (M_1, g_1) vanishes. With the additional assumption that (M_1, g_1) is Einstein, we get $R_{(1)00} = R_{(1)11} = R_{(1)0\hat{A}} = R_{(1)1\hat{A}} = 0$ (here $\hat{A} = 2$ only), and as above the Weyl tensor is of type D with $\Phi_{ii}^A = 0$.

Similarly, for any $n_1 > 3$, if (M_1, g_1) is an Einstein space the only non-zero mixed Weyl components (12) will have boost weight zero, and the non-mixed components (14) simplify considerably. As a particular consequence, if (M_1, g_1) is an Einstein space of type D, (M, g) will also be of type D (but now $\Phi_{ij}^A \neq 0$, in general)—this is the case, for example, of uniform black strings/branes (either static or rotating, see also the discussion concluding this section). If (M_1, g_1) is of constant curvature, (M, g) will be of type D with $\Phi_{ij}^A = 0$ (or O)—this includes the higher-dimensional magnetic Bertotti–Robinson solutions [29]. One can consider other special cases using similar simple arguments.

A spacetime conformal to a direct product spacetime is called a *warped product* spacetime if the conformal factor depends only on one of the two coordinate sets x^A , x^I (see, e.g., [1]). Obviously, the algebraic type of two conformal spaces is the same¹⁰. Some of the results presented above can thus be straightforwardly generalized to the more general case of warped products. For example,

Proposition 3. In arbitrary dimension, a warped spacetime with a one-dimensional Lorentzian (timelike) factor can only be of type G, I_i , D (with $\Phi_{ii}^A = 0$) or O.

This case includes, in particular, the conclusion of section 3 for static spacetimes. As warped non-static/non-stationary examples we can mention the de Sitter universe (in global coordinates) and FRW cosmologies. For n = 4 proposition 3 reduces to a result of [32].

Furthermore,

Proposition 4. In arbitrary dimension, a warped spacetime with a two-dimensional Lorentzian factor can only be of type D (with $\Phi_{ij}^A = 0$) or O.

Again compare with [32] for n = 4. Note that in this case the line element can always be cast in one of the two (conformally related) forms $ds^2 = 2A(u, v) du dv +$ $f(u, v)h_{IJ}(x) dx^I dx^J$ or $ds^2 = 2\tilde{f}(x)A(u, v) du dv + g_{IJ}(x) dx^I dx^J$ (so that multiple WANDs are given by ∂_u and ∂_v), which include a number of known spacetimes. For example, the first possibility includes all spherically symmetric spacetimes, hence as a special case of proposition 4 we have

Proposition 5. In arbitrary dimension, a spherically symmetric spacetime is of type D (with $\Phi_{ii}^A = 0$) or O.

For n = 4 this has been known for a long time (see, e.g., [33] and sections 15.2, 15.3 of [1]), and in this case $\Phi_{ij}^A = 0$ means that Ψ_2 is real (see footnote 6). For n > 4, this result has been proven in [34] in the static case.

Other properties of decomposable Weyl tensors were discussed in [2].

¹⁰ This is also true for doubly warped product spacetimes discussed in [31], so that propositions 3 and 4 also hold in that case.

4.2. 'Factorized' geodetic null vector fields

Let us define an *n*-dimensional spacetime (M, g) as the warped product of an n_1 -dimensional Lorentzian space $(M_1, g_{(1)})$ and an n_2 -dimensional Riemannian space $(M_2, g_{(2)})$, with $n = n_1 + n_2$ as in the preceding subsection. Hereafter we shall assume $n_1 \ge 2$. Using the adapted coordinates defined above, the metric can take one of the following two forms:

$$ds^{2} = g_{AB} dx^{A} dx^{B} + f(x^{A})h_{IJ} dx^{I} dx^{J},$$
(15)

$$ds^{2} = \tilde{f}(x^{I})h_{AB} dx^{A} dx^{B} + g_{IJ} dx^{I} dx^{J}, \qquad (16)$$

where g_{AB} , $h_{AB} = g_{(1)AB}$ depend only on the x^A coordinates and g_{IJ} , $h_{IJ} = g_{(2)IJ}$ only on the x^I coordinates.

Given a null vector $\ell_{(1)} = \ell_{(1)}^A \partial_A$ of M_1 , this can be 'lifted' to define a null vector ℓ of M with covariant components $\ell_A = \ell_{(1)A}$ (functions of x^A only) and $\ell_I = 0$. From equations (15), (16) it follows that if $\ell_{(1)}$ is geodetic (and affinely parameterized) in M_1 then ℓ is automatically geodetic (and affinely parameterized) in M. We can thus 'compare' the optical scalars of $\ell_{(1)}$ in M_1 with those of ℓ in M. For the warped metric (15), with the definitions (4) one finds

$$\sigma^{2} = \sigma_{(1)}^{2} + \frac{(n_{1} - 2)n_{2}}{n_{1} + n_{2} - 2} \left[\theta_{(1)} - \frac{1}{2} (\ln f)_{,A} \ell^{A} \right]^{2},$$

$$\theta = \frac{1}{n_{1} + n_{2} - 2} \left[(n_{1} - 2)\theta_{(1)} + \frac{n_{2}}{2} (\ln f)_{,A} \ell^{A} \right],$$

$$\omega^{2} = \omega_{(1)}^{2},$$

(17)

where $\sigma_{(1)}^2$, $\theta_{(1)}$ and $\omega_{(1)}^2$ are the optical scalars of $\ell_{(1)}$ in $(M_1, g_{(1)})$. For the warped metric (16) one has

$$\sigma^{2} = \tilde{f}^{-2} \left[\sigma_{(1)}^{2} + \frac{(n_{1} - 2)n_{2}}{n_{1} + n_{2} - 2} \theta_{(1)}^{2} \right],$$

$$\theta = \frac{n_{1} - 2}{n_{1} + n_{2} - 2} \tilde{f}^{-1} \theta_{(1)},$$

$$\omega^{2} = \tilde{f}^{-2} \omega_{(1)}^{2}.$$
(18)

The special case of direct products is recovered for f, $\tilde{f} = \text{const}$ (which can be rescaled to 1), in which case the shear of the full spacetime originates in the shear and expansion of the Lorentzian factor (while expansion and twist are essentially the same as in $(M_1, g_{(1)})$).

Note that for $n_1 = 2$ the definitions (4) for $\sigma_{(1)}^2$ and $\theta_{(1)}$ become formally singular because of the normalization, but for a Lorentzian 2-space (e.g., $ds^2 = 2A(u, v) du dv$ with the geodetic null vector $\ell = A^{-1}\partial_v$) one has $\ell_{(a;b)}\ell^{(a;b)} = \ell^a{}_{;a} = \ell_{[a;b]}\ell^{a;b} = 0$, so that we can essentially take $\sigma_{(1)}^2 = \theta_{(1)} = \omega_{(1)} = 0$ and formulae (17), (18) still hold.

The results of this section can be applied to several known solutions. For example, static [rotating] black strings and branes (i.e., direct products of Schwarzschild [Kerr] cross a flat space) are type D vacuum spacetimes with two shearing, expanding, twistfree [twisting] multiple WANDs. As such, they clearly 'violate' the Golberg–Sachs theorem. In addition, spherically symmetric solutions in any dimensions (which necessarily take the metric form (15) with $n_1 = 2$) are type D spacetimes with two shearfree, expanding, twistfree multiple WANDs (independently of any specific field equations; in the 'exceptional case' ($\ln f$)_{.A} $\ell^A = 0$ the vector ℓ is non-expanding, e.g. for Bertotti–Robinson/Nariai geometries or for null generators of horizons).

5. Type D Einstein spacetimes in higher dimensions

From the results of the previous sections it follows that type D spacetimes are the simplest nontrivial examples of static/stationary ('expanding' and with an appropriate reflection)/warped spacetimes. Therefore, we will focus on type D spacetimes in general (without assuming staticity etc). Recall that the quantities/symbols used below (e.g. Φ_{ij} , L_{ij} , D) are defined in section 2.

5.1. Algebraic conditions following from the Bianchi equations

Various contractions of Bianchi identities

$$R_{abcd;e} + R_{abde;c} + R_{abec;d} = 0 \tag{19}$$

lead to a set of first-order PDEs for frame components of the Riemann tensor given in appendix B of [8]. In the following we shall concentrate on Einstein spaces (defined by $R_{ab} = \frac{R}{n}g_{ab}$), for which the same set of equations also holds unchanged for components of the Weyl tensor. In the case of algebraically special spacetimes, some of these differential equations reduce to algebraical equations due to the vanishing of some components of the Weyl tensor. Here, we derive algebraic conditions following from the Bianchi equations for type D Einstein spacetimes. These conditions will be employed in subsequent sections.

In particular, by contracting (19) with $m^{(i)}$, ℓ , $m^{(j)}$, $m^{(k)}$ and ℓ (equation (B.8) in [8]) and assuming to have a type D Einstein space we get the first algebraic condition

$$\Phi_{ij}L_k - \Phi_{ik}L_j + 2\Phi_{kj}^A L_i - C_{isjk}L_s = 0,$$
⁽²⁰⁾

where we denoted L_{i0} by L_i . We will also denote $L_i L_i$ by L.

The second algebraic equation follows from equation (B.15, [8])

$$0 = 2 \left(\Phi_{jk}^{A} L_{im} + \Phi_{mj}^{A} L_{ik} + \Phi_{km}^{A} L_{ij} + \Phi_{ij} A_{mk} + \Phi_{ik} A_{jm} + \Phi_{im} A_{kj} \right) + C_{isjk} L_{sm} + C_{ismj} L_{sk} + C_{iskm} L_{sj}$$
(21)

and contraction of k with i leads to

$$0 = S\Phi_{mj}^{A} + \Phi A_{jm} - (\Phi_{mi}^{S} + \Phi_{mi}^{A}) S_{ij} + (\Phi_{ji}^{S} + \Phi_{ji}^{A}) S_{im} + 2 (\Phi_{im}^{A} A_{ij} - \Phi_{ij}^{A} A_{im}) + \frac{1}{2} C_{ismj} A_{si}.$$
(22)

By contracting m with j in equation (B.12) from [8] we get

 $2D\Phi_{ik}^{S} = 4\Phi_{ii}^{A}A_{ki} + \Phi_{ki}L_{ii} + \Phi_{ii}L_{jk} - \Phi_{ki}S - \Phi_{ki}L_{ik} - 2\Phi_{is}^{S}L_{sk}$

$$-2\Phi_{sk}^{s} \stackrel{s}{M}_{i0} - 2\Phi_{is}^{s} \stackrel{s}{M}_{k0} + C_{ijks}L_{sj}, \tag{23}$$

where we employed $C_{iskj} \stackrel{s}{M}_{j0} + C_{ijks} \stackrel{s}{M}_{j0} = 0 (\stackrel{s}{M}_{j0} + \stackrel{j}{M}_{s0} = 0, \text{ cf [8]}).$

The symmetric part of equation (B.5, [8]) and equation (B.3) (that is equivalent to the antisymmetric part of (B.5)) give, respectively,

$$2D\Phi_{ik}^{S} = -2\Phi S_{ik} + (-2\Phi_{is} + \Phi_{si})L_{sk} + (-2\Phi_{ks} + \Phi_{sk})L_{si} - 2\Phi_{sk}^{S} \stackrel{s}{M}_{i0} - 2\Phi_{is}^{S} \stackrel{s}{M}_{k0}, \quad (24)$$

$$2D\Phi_{ik}^{A} = -2\Phi A_{ik} + (-2\Phi_{is} + \Phi_{si})L_{sk} - (-2\Phi_{ks} + \Phi_{sk})L_{si} - 2\Phi_{sk}^{A} \stackrel{\circ}{M}_{i0} + 2\Phi_{si}^{A} \stackrel{\circ}{M}_{k0} .$$
(25)

By subtracting (24) from (23) we finally obtain the third algebraic equation

$$0 = -\Phi_{ki}S + \Phi L_{ki} + \Phi_{kj}L_{ij} + 4\Phi^A_{ij}A_{kj} + (2\Phi_{kj} - \Phi_{jk})L_{ji} + 2\Phi^A_{ij}L_{jk} + C_{ijks}L_{sj}.$$
 (26)

Its antisymmetric part is, thanks to $C_{ikjm}A_{mj} = 2C_{ijks}A_{sj}$, equal to equation (22) and its symmetric part reads

$$0 = -S\Phi_{ik}^{S} + \Phi S_{ik} + \Phi_{ij}^{S}S_{jk} + \Phi_{kj}^{S}S_{ij} + 3\left(\Phi_{ij}^{A}S_{jk} + \Phi_{kj}^{A}S_{ji}\right) + C_{ijks}S_{sj}.$$
 (27)

Equations (20), (22) and (27) will be extensively used in the following sections.

In passing, let us observe here in what sense the n = 4 case is unique. Recalling footnote 6, from (20) we get $L_i = 0$ (geodetic property) unless $\Phi_{ij} = 0$ (trivial case of zero Weyl tensor); equation (22) is identically satisfied (noting that necessarily $\Phi_{ij}^A \propto A_{ij}$ when n = 4); equation (27) implies $S_{ij} \propto \delta_{ij}$ (vanishing shear) again unless $\Phi_{ij} = 0$. Thus, for n = 4 we correctly recover the standard Goldberg–Sachs result (here restricted to type D spacetimes) that multiple WANDs (PNDs) are geodetic and shearfree in vacuum (and Einstein) spaces [1]. The situation in higher dimensions, which is qualitatively different from the n = 4 case, is studied in the following sections.

5.2. WANDs in 'generic' vacuum type D and II spacetimes in arbitrary dimension are geodetic

In this section, we study equation (20) in order to determine under which circumstances the multiple WAND ℓ is geodetic.

By contracting i with k in (20) and using (6) we get

$$\left(3\Phi_{ij}^{A} - \Phi_{ij}^{S}\right)L_{i} = \Phi L_{j} \tag{28}$$

and after multiplying (28) by L_i we obtain

$$\Phi_{ij}^{S}L_{i}L_{j} = -\Phi L. \tag{29}$$

By multiplying (20) by $L_i L_j$ and using (29) we get

$$L\left(3\Phi_{ik}^{A}L_{i}+\Phi_{ik}^{S}L_{i}+\Phi L_{k}\right)=0.$$
(30)

Thus, either L = 0 or

$$\left(-3\Phi_{ii}^{A} - \Phi_{ii}^{S}\right)L_{i} = \Phi L_{j}.$$
(31)

By adding and subtracting (28) and (31) we get

$$\Phi_{ij}^{S}L_{i} = -\Phi L_{j}, \qquad \Phi_{ij}^{A}L_{i} = 0.$$
(32)

Finally, multiplying (20) by L_i and using (32) we get

$$L\Phi_{ij}^{A} = 0. \tag{33}$$

This implies that for a type D vacuum spacetime with non-vanishing Φ_{ij}^A in arbitrary dimension corresponding WANDs are geodetic.

In the case with vanishing Φ_{ij}^A , let us choose a frame in which Φ_{ij}^S is diagonal $\Phi_{ij}^S = \text{diag}\{p_{(2)}, p_{(3)}, \dots, p_{(n-1)}\}$. Then from the first equation (32) it follows

$$(p_{(i)} + \Phi)L_i = 0, \tag{34}$$

where (from now on) we do *not* sum over indices in brackets. If $p_{(i)} \neq -\Phi, \forall i$, then $L_i = 0, \forall i$, i.e. ℓ is geodetic.

Note that so far we have employed only equation (20), which corresponds to equation (B.8) in [8] and which does not contain Weyl tensor components with negative boost order. Consequently, the same conclusions also hold for type II Einstein spacetimes.

Proposition 6. In arbitrary dimension, multiple WANDs of type II and D Einstein spacetimes are geodetic if at least one of the following conditions is satisfied:

(i) Φ_{ij}^A is non-vanishing;

(ii) for all eigenvalues of Φ_{ii}^S : $p_{(i)} \neq -\Phi$.

Note that the above argument cannot be extended to more special algebraic classes of spacetimes since it relies on the fact that some Weyl components with boost weight zero are non-vanishing. However, it was already shown in [8] that multiple WANDs in type N and III vacuum spacetimes are geodetic (in that case with no need of extra assumptions). Therefore, we can conclude that under most 'generic' conditions multiple WANDs are geodetic. Note, however, that certain special type D vacuum solutions with $\Phi_{ij}^A = 0$ and $p_{(i)} = -\Phi$ (for some *i*) admit non-geodetic multiple WANDs. An explicit example of such a spacetime is given in section 5.4.

5.3. Vacuum type D spacetimes with a 'shearfree' WAND

The algebraic equations (22) and (27) are quite complicated in a general dimension and thus here we will limit ourselves to the 'shearfree' case. This is of interest since it includes, for instance, the Robinson–Trautman solutions containing static black holes [35].

With the 'shearfree' condition

$$S_{ij} = \frac{s}{n-2}\delta_{ij},\tag{35}$$

equation (27) leads for $S \neq 0$ to

$$\Phi_{ij}^{S} = \frac{\Phi}{n-2}\delta_{ij} \qquad (S \neq 0), \tag{36}$$

whereas it is identically satisfied for S = 0. In the rest of this subsection, we thus consider only the 'expanding' case $S \neq 0$. For Φ_{ij}^S in the form (36) with $\Phi \neq 0$ condition (ii) of proposition 6 is satisfied and thus the WAND ℓ is geodetic.

Proposition 7. In arbitrary dimension, multiple 'shearfree' and 'expanding' WAND in a type D Einstein spacetime is geodetic whenever $\Phi_{ij} \neq 0$.

Note that Φ_{ij} has to be non-zero for type D spacetimes in four and five dimensions. Thus all such shearfree WANDs are geodetic¹¹. On the other hand, spacetimes with $\Phi_{ij} = 0$ are not necessarily conformally flat for n > 5 (C_{ijkl} can be non-vanishing, and in that case equation (20) reduces to $C_{isjk}L_s = 0$) and in fact in section 5.4 we will present an example of such a type D vacuum spacetime with a non-geodetic 'shearfree' multiple WAND.

Furthermore, using (35) and (36), equation (22) reads

$$0 = \frac{n-4}{n-2}S\Phi_{ij}^{A} + \Phi A_{ji} + 2\left(\Phi_{ki}^{A}A_{kj} + \Phi_{ik}^{A}A_{ki}\right) + \frac{1}{2}C_{kmij}A_{mk}.$$
(37)

As mentioned above this is identically satisfied for n = 4. For n > 4 (and $S \neq 0$), if one assumes $A_{ij} = 0$ it gives $\Phi_{ij}^A = 0$, while assuming $\Phi_{ij}^A = 0$ leads to $C_{kmij}A_{mk} = 2\Phi A_{ij}$. On the other hand, from equation (25) with (35) and (36) we see that $\Phi_{ij}^A = 0$ implies $A_{ij} = 0$, unless $\Phi = 0$ (in which case the full Φ_{ij} would be zero). We can thus summarize these results in

Proposition 8. For a multiple 'shearfree' and 'expanding' WAND in a type D Einstein spacetime in n > 4 dimensions the following implications hold:

 $\begin{array}{ll} (i) \ A_{ij} = 0 \quad \Rightarrow \quad \Phi^A_{ij} = 0. \\ (ii) \ \Phi^A_{ij} = 0, \ \Phi^S_{ij} \neq 0 \quad \Rightarrow \quad A_{ij} = 0. \\ (iii) \ \Phi^A_{ij} = 0, \ \Phi^S_{ij} = 0 \quad \Rightarrow \quad C_{kmij}A_{mk} = 0. \end{array}$

¹¹ In fact, for n = 4 from the Goldberg–Sachs theorem we already knew that all multiple WANDs are automatically shearfree and geodetic.

Note that for an arbitrary odd-dimensional spacetime with a geodetic and shearfree WAND one has $A_{ij} = 0$ [10] and thus in the expanding case, $\theta \neq 0$, by (i) Φ_{ij}^A also necessarily vanish. Note also that the assumptions of (i) (i.e., $\sigma_{ij} = 0 = A_{ij}, \theta \neq 0$) uniquely identify the Robinson–Trautman spacetimes (which are of type D for n > 4) in any dimensions and indeed $\Phi_{ij}^A = 0$ for the corresponding Weyl tensor [35]. In general, $\Phi_{ij}^S = \frac{\Phi}{n-2}\delta_{ij} \neq 0$ for Robinson–Trautman solutions [35] and by proposition 7 the multiple WANDs are thus geodetic; however, in the next subsection we present a very special Robinson–Trautman solution with vanishing Φ_{ij}^S and with a non-geodetic WAND.

5.4. An example of type D vacuum spacetimes with a non-geodetic WAND

The conclusions in the preceding subsections about the geodetic character of multiple WANDs cannot be (in contrast to the n = 4 case) extended to the most general case. In fact, here we point out that a special subclass of the Robinson–Trautman solutions [35] in $n \ge 7$ dimensions represents type D vacuum spacetimes (with a possible cosmological constant) for which one of the multiple WANDs is non-geodetic. Namely, let us consider the vacuum family [35, 36]

$$ds^{2} = r^{2}h_{ij} dx^{i} dx^{j} - 2 du dr - 2H du^{2},$$

$$2H = K - 2r(\ln P)_{,u} - \frac{2\Lambda}{(n-2)(n-1)}r^{2} \qquad (K = 0, \pm 1),$$
(38)

where $P^2 = (\det h_{ij})^{1/(2-n)}$ and h_{ij} represents an arbitrary (n-2)-dimensional Einstein space (i, j = 2, ..., n-1 are, exceptionally, coordinate indices in this subsection). Using a suitable frame based on the null vectors

$$\ell = \partial_r, \qquad n = -\partial_u + H \partial_r, \tag{39}$$

the only non-vanishing components of the Weyl tensor have boost weight zero and are given by [35]

$$C_{ijkl} = r^2 (\mathcal{R}_{ijkl} - 2Kh_{i[k}h_{l]j}), \tag{40}$$

where \mathcal{R}_{ijkl} is the Riemann tensor associated with h_{ij} . This implies that the spacetime (38) is of type D, with $\Phi_{ij} = 0$, and that both ℓ and n are multiple WANDs. Now, the vector ℓ is geodetic, shearfree and twistfree by construction [35]. Next, one can easily show that

$$\nabla_n n = -H_{,r} n + H_{,i} \,\mathrm{d} x^i,\tag{41}$$

where, by (38), $H_{,i} = -r(\ln P)_{,ui}$. Therefore, *n* is geodetic if and only if $(\ln P)_{,ui} = 0 \Leftrightarrow P = p_1(u)p_2(x^2, x^3, ...)$. For a general (non-factorized) function *P* the multiple WAND *n* is thus non-geodetic (one can also easily check that it is 'shearfree', 'twistfree' and 'expanding'). A simple explicit example of such spacetimes is obtained by extending to any $n \ge 7$ the n = 7 dimensional solution discussed in [36], i.e. by taking in equation (38)

$$K = -1, \qquad P = f(u, z)^{-1/2} [\rho^{n-5} (\det \eta_{\alpha\beta})^{1/2}]^{1/(2-n)},$$

$$h_{ij} dx^{i} dx^{j} = f(u, z) \left[dz^{2} + V(\rho) d\tau^{2} + \frac{1}{V(\rho)} d\rho^{2} + \rho^{2} \eta_{\alpha\beta} dx^{\alpha} dx^{\beta} \right], \qquad (42)$$

$$f(u, z) = \frac{4b(u)e^{2z/l}}{l^{2}[e^{2z/l} - b(u)]^{2}}, \qquad V(\rho) = \left(1 - \frac{\mu}{\rho^{n-6}} - \frac{\rho^{2}}{l^{2}}\right),$$

where $z \equiv x^2$, $\tau \equiv x^3$, $\rho \equiv x^4$, $\eta_{\alpha\beta} = \eta_{\alpha\beta}(x^5, x^6, ...)$ is the metric of an (n-5)-dimensional unit sphere $(\alpha, \beta = 5, ..., n-1)$, μ and l are constants and b(u) > 0 is an arbitrary function. The multiple WAND n is non-geodetic as long as $db/du \neq 0$. Note that there is no contradiction with the results of the previous subsections precisely because $\Phi_{ij} = 0$ here.

6. Type D vacuum spacetimes in five dimensions

Let us now study the five-dimensional case. Note that the algebraic relation (6) between $-2\Phi_{ij}^S$ and C_{ijkl} is equivalent to the relation between the Ricci and the Riemann tensor of an (m-2)-dimensional space. Therefore, in five dimensions C_{ijkl} is equivalent to Φ_{ij}^S and thus a type D Weyl tensor in five dimensions is fully determined by Φ_{ij} . In fact, for n = 5 it is possible to solve the second constraint from (6) for C_{ijkl} :

$$C_{ijkl} \stackrel{(n=5)}{=} 2\left(\delta_{il}\Phi^{S}_{jk} - \delta_{ik}\Phi^{S}_{jl} - \delta_{jl}\Phi^{S}_{ik} + \delta_{jk}\Phi^{S}_{il}\right) - \Phi(\delta_{il}\delta_{jk} - \delta_{ik}\delta_{jl}).$$
(43)

Thus, in the five-dimensional case the algebraic equations we consider, (20), (21), (22), (27), can be expressed in terms of Φ_{ij} , L_i , and L_{ij} . Plugging (43) into (20), recalling equation (32) and contracting with L_k one finds the equation

$$L\Phi_{ii}^{S} + 2\Phi L_i L_i - \Phi L\delta_{ii} = 0.$$

$$\tag{44}$$

For n = 5, equation (21) takes the form

$$0 = \Phi_{jk}^{A} L_{im} + (\Phi_{im}^{A} + 3\Phi_{im}^{S}) A_{kj} + \Phi_{mj}^{A} L_{ik} + (\Phi_{ik}^{A} + 3\Phi_{ik}^{S}) A_{jm} + \Phi_{km}^{A} L_{ij} + (\Phi_{ij}^{A} + 3\Phi_{ij}^{S}) A_{mk} + \delta_{ij} (\Phi_{ms}^{S} L_{sk} - \Phi_{ks}^{S} L_{sm}) + \delta_{ik} (\Phi_{js}^{S} L_{sm} - \Phi_{ms}^{S} L_{sj}) + \delta_{im} (\Phi_{ks}^{S} L_{sj} - \Phi_{js}^{S} L_{sk}) + \Phi[\delta_{ij} A_{km} + \delta_{ik} A_{mj} + \delta_{im} A_{jk}].$$
(45)

Equation (22) reduces to

$$0 = \Phi_{mj}^{A}S + 2\Phi A_{jm} + \Phi_{ji}^{A}(S_{im} + 2A_{im}) + \Phi_{im}^{A}(S_{ij} + 2A_{ij}) + \Phi_{ji}^{S}(S_{im} - 2A_{im}) + \Phi_{mi}^{S}(-S_{ij} + 2A_{ij}),$$
(46)

and equation (27) has the form

$$3\left[\left(\Phi_{ij}^{S} + \Phi_{ij}^{A}\right)S_{jk} + \left(\Phi_{kj}^{S} + \Phi_{kj}^{A}\right)S_{ji} - S\Phi_{ki}^{S}\right] = \delta_{ik}\left(2\Phi_{js}^{S}S_{js} - \Phi S\right).$$
 (47)

In the following sections we study (non-)geodecity of multiple WANDs (section 6.1), spacetimes admitting non-twisting WANDs $A_{ij} = 0$ (section 6.2) and spacetimes with $\Phi_{ij}^A = 0$ (section 6.3).

6.1. Geodeticity of multiple WANDs

It is interesting to return now to equation (20), which is related to the (non-)geodetic character of multiple WANDs and in five dimensions implies (44). Since we already know from proposition 6 that WANDs are necessarily geodetic when $\Phi_{ij}^A \neq 0$, let us focus here on the case $\Phi_{ij}^A = 0$. If $\Phi = 0$ we see that either L = 0 or $\Phi_{ij}^S = 0$, the latter case being now a conformally flat spacetime. Therefore, an n = 5 type D Einstein spacetime requires ($\Phi_{ij}^A = 0$ and) $\Phi \neq 0$ in order to admit a non-geodetic multiple WAND. In this case, it follows from (44) that there exists an eigenframe of Φ_{ij}^S such that

$$\Phi_{ij}^{S} = \Phi \operatorname{diag}(1, 1, -1), \qquad L_2 = L_3 = 0, \tag{48}$$

so that $L_4 \neq 0$ is responsible for the WAND ℓ being non-geodetic. Such a spacetime is necessarily shearing since the 'canonical' form of Φ_{ij}^S given in equation (48) is not compatible with that of equation (36). It would be interesting to find such a five-dimensional vacuum type D spacetime with a non-geodetic WAND or prove that such a spacetime does not exist.

To summarize,

Proposition 9. In five dimensions, the only type D Einstein spacetimes with non-geodetic multiple WAND ℓ are those satisfying $\Phi_{ik}^A = 0$ and $\Phi_{ik}^S \neq 0$, $\Phi_{ik}^S = \text{diag}\{\Phi, \Phi, -\Phi\}$.

6.2. 'Non-twisting' case $A_{ij} = 0$

In the non-twisting case $A_{ij} = 0$, equation (46) reduces to

$$\Phi_{ji}S_{im} - \Phi_{mi}S_{ij} + \Phi^A_{mi}S = 0.$$
⁽⁴⁹⁾

Now we can, without loss of generality, choose a frame in which the symmetric matrix S_{ij} is diagonal:

$$S_{ij} = \text{diag}(s_{(2)}, s_{(3)}, s_{(4)}).$$
(50)

Then, equations (49) and (47) take the form (recall that we do not sum over indices in brackets)

$$\Phi_{ik}^{S}(s_{(k)} - s_{(i)}) + \Phi_{ik}^{A}(s_{(k)} + s_{(i)} - S) = 0,$$

$$\Phi_{ik}^{S}(s_{(k)} + s_{(i)} - S) + \Phi_{ik}^{A}(s_{(k)} - s_{(i)}) = \frac{1}{3}\delta_{ik} \left(2\Phi_{js}^{S}S_{js} - \Phi S\right).$$
(51)

Now let us study components of the two above equations for $i \neq k$. By summing the two above equations we get

$$(2s_{(k)} - S)\left(\Phi_{ik}^{S} + \Phi_{ik}^{A}\right) = 0 \qquad (i \neq k).$$
(52)

In the 'generic' case with $2s_{(i)} \neq S \forall i$, this implies

$$\Phi_{ik}^{A} = 0 = \Phi_{ik}^{S} \quad \text{for} \quad i \neq k.$$
(53)

Consequently, Φ_{ii}^{S} is also diagonal and from equation (51)

$$\Phi_{ij}^{S} = \operatorname{diag}(p_{(2)}, p_{(3)}, p_{(4)}), \qquad p_{(i)} = \frac{2\Phi_{js}^{S}S_{js} - \Phi S}{3(2s_{(i)} - S)}.$$
(54)

Using (54), it is straightforward to express (two of) $p_{(i)}$ in terms of $s_{(i)}$ solving the linear relations (which are not all independent):

$$(s_{(2)} - s_{(3)} - s_{(4)})p_{(2)} = (-s_{(2)} + s_{(3)} - s_{(4)})p_{(3)},$$
(55)

$$(s_{(2)} - s_{(3)} - s_{(4)})p_{(2)} = (-s_{(2)} - s_{(3)} + s_{(4)})p_{(4)},$$
(56)

$$(-s_{(2)} + s_{(3)} - s_{(4)})p_{(3)} = (-s_{(2)} - s_{(3)} + s_{(4)})p_{(4)}.$$
(57)

Thus,

Proposition 10. In five dimensions, in the 'generic' $(2s_{(i)} \neq S \forall i)$ non-twisting $(A_{ij} = 0)$ type D Einstein spacetime, Φ_{ij}^A also vanishes and Φ_{ij}^S can be diagonalized together with S_{ij} .

Note that special cases with $2s_{(i)} = S$ for some *i* have to be treated separately:

- (1) If one of $s_{(i)} = S/2$, e.g. $s_{(4)} = S/2$, and the others differ from S/2, 0 then only $\Phi_{44}^S \neq 0$, all other components of $\Phi_{ij}^S = 0$ and $\Phi_{ij}^A = 0$.
- (2) If, e.g., $s_{(2)} = s_{(3)} = S/2$, $s_{(4)} = 0$ then $\Phi_{24}^S = \Phi_{34}^S = \Phi_{44}^S = \Phi_{24}^A = \Phi_{34}^A = 0$, the other components $(\Phi_{22}^S, \Phi_{33}^S, \Phi_{23}^S, \Phi_{23}^A)$ are arbitrary.
- 6.3. *Case* $\Phi_{ii}^{A} = 0$

For $\Phi_{ii}^A = 0$, equations (46), (25) and (47) take the form

$$2\left(\Phi_{mi}^{S}A_{ij} - \Phi_{ji}^{S}A_{im} + \Phi A_{jm}\right) + \Phi_{ji}^{S}S_{im} - \Phi_{mi}^{S}S_{ij} = 0,$$
(58)

$$-\Phi_{im}^{S}A_{ij} + \Phi_{ji}^{S}A_{im} + 2\Phi A_{jm} + \Phi_{ji}^{S}S_{im} - \Phi_{mi}^{S}S_{ij} = 0,$$
(59)

$$3\left(\Phi_{ij}^{S}S_{jk} + \Phi_{kj}^{S}S_{ji} - S\Phi_{ki}^{S}\right) = \delta_{ik}\left(2\Phi_{jl}^{S}S_{jl} - \Phi S\right).$$
(60)

In section 6.2, it was efficient to choose a frame in which S_{ij} was diagonal; however, now it is more efficient to choose a frame in which Φ_{ij}^S is diagonal, $\Phi_{ij}^S = \text{diag}\{p_{(2)}, p_{(3)}, p_{(4)}\}$. Then, we obtain from (58)–(60) the following set of equations:

$$(2p_{(m)} + 2p_{(j)} - 2\Phi)A_{mj} + S_{mj}(p_{(j)} - p_{(m)}) = 0,$$
(61)

$$(-p_{(m)} - p_{(j)} - 2\Phi)A_{mj} + S_{mj}(p_{(j)} - p_{(m)}) = 0,$$
(62)

$$3(p_{(i)} + p_{(k)})S_{ik} = \delta_{ik} \left(3Sp_{(i)} + 2\Phi_{jl}^{S}S_{jl} - \Phi S\right).$$
(63)

In the 'generic' case $p_{(i)} + p_{(k)} \neq 0, \forall i, k$, from equation (63)

$$S_{ik} = \text{diag}\{s_{(2)}, s_{(3)}, s_{(4)}\}, \qquad s_{(i)} = \frac{S}{2} + \frac{2\Phi_{jl}^S S_{jl} - \Phi S}{6p_{(i)}}.$$
 (64)

From (64) we get the relations (which can be solved to fix two of the s_i , if desired)

$$s_{(2)}p_{(3)}(p_{(2)} + p_{(4)}) = s_{(3)}p_{(2)}(p_{(3)} + p_{(4)}),$$
(65)

$$s_{(2)}p_{(4)}(p_{(2)} + p_{(3)}) = s_{(4)}p_{(2)}(p_{(3)} + p_{(4)}),$$
(66)

$$s_{(3)}p_{(4)}(p_{(2)} + p_{(3)}) = s_{(4)}p_{(3)}(p_{(2)} + p_{(4)}).$$
(67)

Subtracting (61) and (62) we obtain $(p_{(m)} + p_{(j)})A_{mj} = 0$ and thus in the 'generic' case $p_{(m)} + p_{(j)} \neq 0, \forall m, j,$

$$A_{mj} = 0. ag{68}$$

Proposition 11. In five dimensions, the multiple WAND ℓ in a 'generic' $(p_{(i)} + p_{(j)} \neq 0, \forall i, j)$ type D Einstein spacetime with $\Phi_{ik}^A = 0$ and $\Phi_{ik}^S \neq 0$ is geodetic and non-twisting $(A_{ij} = 0)$ and Φ_{ik}^S and S_{ij} can be diagonalized together.

There are some special cases to be treated:

- *Case* (*a*)—one $p_{(i)} = 0$ and $\Phi \neq 0$: without loss of generality we choose $p_{(2)} = 0$, then from (61)–(63) $2\Phi_{il}^S S_{jl} \Phi S = 0$, $S_{ij} = \text{diag}\{0, S/2, S/2\}$, $A_{mj} = 0$.
- Case (b)—only one $p_{(i)} \neq 0$: without loss of generality we choose $p_{(4)} \neq 0$, $p_{(2)} = p_{(3)} = 0$ then from (61)–(63) $2\Phi_{jl}^S S_{jl} \Phi S = 0$, $s_{(2)} + s_{(3)} = s_{(4)} = S/2$ and S_{23} is arbitrary, A_{ij} vanishes.
- Case (c)—only one pair satisfies p_(m) + p_(j) = 0, p_(j) ≠ 0: without loss of generality we choose p₍₃₎ + p₍₄₎ = 0, i.e. p₍₂₎ = Φ, then the diagonal components of S_{ij} still satisfy (64), from (61)–(63) S₃₄ is arbitrary and

$$(p_{(m)} + p_{(j)})A_{mj} = 0, \qquad 2\Phi A_{mj} = (p_{(j)} - p_{(m)})S_{mj}$$
(69)

and thus if $\Phi \neq 0$, $A_{34} = -\frac{p_{(3)}}{\Phi}S_{34}$. If $\Phi = 0$, then $S_{34} = 0$ and S_{ij} is diagonal and A_{23} is arbitrary.

• *Case* (*d*)—*two pairs satisfy* $p_{(m)} + p_{(j)} = 0$: without loss of generality we choose $p_{(2)} = p_{(3)} = -p_{(4)} = \Phi$. From (64) it follows that the diagonal components of S_{ij} , $s_{(2)}$ and $s_{(3)}$ vanish and $s_{(4)}$ is arbitrary. Equation (63) implies that S_{24} and S_{34} are arbitrary and from equation (69) we get $A_{23} = 0$, $A_{24} = -S_{24}$, $A_{34} = -S_{34}$. This case is the non-geodetic case (48) from section 6.1.

6.4. An example—Myers-Perry black hole

As an illustrative example we give S_{ij} , A_{ij} , Φ_{ij}^S and Φ_{ij}^A for the five-dimensional Myers–Perry black hole [9]:

$$ds^{2} = \frac{\rho^{2}}{4\Delta} dx^{2} + \rho^{2} d\theta^{2} - dt^{2} + (x + a^{2}) \sin^{2} \theta d\phi^{2} + (x + b^{2}) \cos^{2} \theta d\psi^{2} + \frac{r_{0}^{2}}{\rho^{2}} (dt + a \sin^{2} \theta d\phi + b \cos^{2} \theta d\psi)^{2},$$

where

$$\rho^2 = x + a^2 \cos^2 \theta + b^2 \sin^2 \theta, \qquad \Delta = (x + a^2)(x + b^2) - r_0^2 x$$

Two (multiple, geodetic) WANDs (related by reflection symmetry) are given by [7]

$$\ell = \frac{(x+a^2)(x+b^2)}{\Delta} \left[\partial_t - \frac{a}{x+a^2} \partial_\phi - \frac{b}{x+b^2} \partial_\psi \right] + 2\sqrt{x} \partial_x, \tag{70}$$

$$n = \alpha \left(\frac{(x+a^2)(x+b^2)}{\Delta} \left[\partial_t - \frac{a}{x+a^2} \partial_\phi - \frac{b}{x+b^2} \partial_\psi \right] - 2\sqrt{x} \partial_x \right),$$
(71)

where we chose $\alpha = -\Delta/2\rho^2 x$ in order to satisfy the normalization condition $\ell \cdot n = 1$.

As a basis of spacelike vectors we choose three eigenvectors of S_{ij} :

$$m^{(2)} = \frac{1}{\rho} \partial_{\theta},$$

$$m^{(3)} = \frac{1}{\sqrt{x}\chi} (-ab\partial_{t} + b\partial_{\phi} + a\partial_{\psi}),$$

$$m^{(4)} = \frac{1}{\rho\chi} [(a^{2} - b^{2})\sin\theta\cos\theta\partial_{t} - a\tan^{-1}\theta\partial_{\phi} + b\tan\theta\partial_{\psi}],$$
(72)

with $\chi = \sqrt{a^2 \cos^2 \theta + b^2 \sin^2 \theta}$. In this frame,

$$S_{ij} = \begin{pmatrix} \frac{\sqrt{x}}{\rho^2} & 0 & 0\\ 0 & \frac{1}{\sqrt{x}} & 0\\ 0 & 0 & \frac{\sqrt{x}}{\rho^2} \end{pmatrix}, \qquad A_{ij} = \frac{\chi}{\rho^2} \begin{pmatrix} 0 & 0 & -1\\ 0 & 0 & 0\\ 1 & 0 & 0 \end{pmatrix},$$
(73)

and

$$\Phi_{ij}^{S} = \frac{r_0^2}{\rho^4} \begin{pmatrix} \frac{\rho^2 - 2x}{\rho^2} & 0 & 0\\ 0 & -1 & 0\\ 0 & 0 & \frac{\rho^2 - 2x}{\rho^2} \end{pmatrix}, \qquad \Phi_{ij}^{A} = \frac{2r_0^2 \chi \sqrt{x}}{\rho^6} \begin{pmatrix} 0 & 0 & 1\\ 0 & 0 & 0\\ -1 & 0 & 0 \end{pmatrix}.$$
 (74)

Note that in the static (Schwarzschild) limit (a = 0 = b so that $\rho^2 = x)$ one has $S_{ij} = \delta_{ij}/\sqrt{x}$ and $\sigma_{ij} = 0 = A_{ij}$, and indeed for Φ_{ij} we recover the form discussed in subsection 5.3 in the shearfree expanding case and in subsection 6.2 in the 'generic' non-twisting case (with $p_{(2)} = p_{(3)} = p_{(4)}$).

7. Discussion

Let us finally outline the main results presented in the paper.

In the first part of the paper (sections 3 and 4), we studied the constraints on Weyl types of a spacetime following from various assumptions on geometry. It turns out that

- Static spacetimes are of types G, I_i , D or conformally flat (proposition 1).
- 'Expanding' stationary spacetimes with appropriate reflection symmetry belong to these types as well (proposition 2).
- Warped spacetimes with one-dimensional Lorentzian factor are again of types G, I_i, D and O (proposition 3).
- Warped spacetimes with two-dimensional Lorentzian factor are necessarily of types D or O (proposition 4), in particular this also applies to spherically symmetric spacetimes (proposition 5).

These results may have useful practical applications in determining the algebraic type of specific spacetimes (or at least in ruling out some types) just by 'inspecting' the given metric and without performing any calculations. This is particularly important in higher dimensions, where it is more difficult to determine the algebraic class of a given metric.

In the second part of the paper (sections 5 and 6), we study the properties of type D vacuum spacetimes in general (without assuming that the spacetime is static, stationary or warped). In five dimensions a type D Weyl tensor is determined by a 3×3 matrix Φ_{ij} with symmetric and antisymmetric parts being Φ_{ij}^A and Φ_{ij}^S , respectively. In general, in the non-twisting case Φ_{ij} is symmetric while in the twisting case antisymmetric part Φ_{ij}^A appears. In higher dimensions n > 5, the $(n - 2) \times (n - 2)$ matrix Φ_{ij} does not contain complete information about the Weyl tensor, but it still plays an important role. The matrix Φ_{ij} can also be used for further classification of type D or II spacetimes, for example according to possible degeneracy of eigendirections of Φ_{ij} . Special classes are also cases with Φ_{ij} being symmetric or vanishing (such examples for $n \ge 7$ are given in section 5.4), etc.

First, we focus on the geodeticity of multiple WANDs in type D vacuum spacetimes (these are always geodetic for n = 4). It was shown that

- The multiple WAND in a vacuum spacetime is geodetic in the 'generic' case, i.e. if $\Phi_{ij}^A \neq 0$ or if all eigenvalues of Φ_{ij}^S are distinct from minus the trace of Φ_{ij} (proposition 6).
- It is also geodetic in the type D, shearfree case whenever $\Phi_{ij} \neq 0$ (proposition 7).
- However, explicit examples of vacuum type D spacetimes with non-geodetic multiple WAND in $n \ge 7$ dimensions are given in section 5.4. This provides us with the first examples of spacetimes 'violating' the geodetic part of the Goldberg–Sachs theorem.
- In five dimensions multiple WANDs are also geodetic when $\Phi_{ij}^A = 0$ and $\Phi_{ij}^S \neq 0$ has a 'generic' form (proposition 11), special cases are discussed in section 6.3.

Properties of the matrix Φ_{ij} , as well as the expansion and twist matrices S_{ij} and A_{ij} , have also been studied:

- For warped spacetimes with a one/two-dimensional Lorentzian factor (thus also for static spacetimes) the antisymmetric part of Φ_{ij}, Φ^A_{ij}, vanishes.
- In vacuum type D spacetimes admitting a shearfree expanding WAND, Φ_{ij}^S is proportional to δ_{ij} and if $A_{ij} = 0$ (this always holds in odd dimensions [10]) then $\Phi_{ij}^A = 0$ and in the case with $\Phi_{ij}^S \neq 0$ also vice versa (proposition 8).
- In five dimensions in a 'generic' Einstein type D non-twisting spacetime, Φ_{ij}^A vanishes and eigendirections of Φ_{ij} coincide with those of S_{ij} (proposition 10).
- In five dimensions in a 'generic' vacuum type D spacetime with symmetric Φ_{ij} , the multiple WAND ℓ is non-twisting and eigendirections of Φ_{ij} and S_{ij} coincide (proposition 11).

These results provide interesting connections between geometric properties of principal null congruences and Weyl curvature. Hopefully, they can also be used for constructing exact type D solutions with particular properties.

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Appendix A. Optics of WANDs in Kerr–NUT–AdS spacetimes in arbitrary dimension

As discussed in section 3.3, the assumption about non-zero 'expansion' in proposition 2 is essential. In this appendix, we study optical properties of WANDs in Kerr–NUT–AdS spacetimes in arbitrary dimension [16] and show that the 'expansion' in these cases is always non-vanishing. These metrics are thus subject to proposition 2. Indeed, it has already been shown in [15] that these spacetimes are of type D. In addition, since the expansion is non-zero, we can expect that possible (still stationary) generalizations of these spacetimes (such as charged black holes) with appropriate reflection symmetry are of types G, I_i or D (see also footnotes 7 and 8). This appendix also extends our example of five-dimensional Myers–Perry given in section 6.4 to the case with NUT parameters and cosmological constant and to arbitrary dimension. Note, however, that now we use convenient but physically less 'transparent' coordinates $(x_1, \ldots, x_m, \psi_0, \ldots, \psi_{m-1})$ in even dimensions n = 2m and $(x_1, \ldots, x_m, \psi_0, \ldots, \psi_m)$ in odd dimensions n = 2m + 1, introduced in [16]. In our calculations, we employ results obtained in [15].

The metric of [16] for even and odd dimensions is, respectively,

$$n = 2m$$
:

$$ds^{2} = \sum_{\mu=1}^{m} \frac{dx_{\mu}^{2}}{Q_{\mu}} + \sum_{\mu=1}^{m} Q_{\mu} \left(\sum_{k=0}^{m-1} A_{\mu}^{(k)} d\psi_{k} \right)^{2},$$
(A.1)

n = 2m + 1:

$$ds^{2} = \sum_{\mu=1}^{m} \frac{dx_{\mu}^{2}}{Q_{\mu}} + \sum_{\mu=1}^{m} Q_{\mu} \left(\sum_{k=0}^{m-1} A_{\mu}^{(k)} d\psi_{k}\right)^{2} + \tilde{S} \left(\sum_{k=0}^{m} A^{(k)} d\psi_{k}\right)^{2}.$$
 (A.2)

The functions Q_{μ} , $A_{\mu}^{(k)}$, $A^{(k)}$ and \tilde{S} depend only on the coordinates (x_1, \ldots, x_m) and their explicit expressions are given in [15, 16].

A.1. Even dimensions, n = 2m

An orthonormal frame of 1-forms $\{e^{(A)}\} = \{e^{(\mu)}, e^{(m+\mu)}\}$ with $A = 1, 2, ..., 2m, \mu = 1, 2, ..., m$,

$$e^{(\mu)} = \frac{\mathrm{d}x_{\mu}}{\sqrt{Q_{\mu}}}, \quad e^{(m+\mu)} = \sqrt{Q_{\mu}} \left(\sum_{k=0}^{m-1} A_{\mu}^{(k)} \,\mathrm{d}\psi_k \right)$$
 (A.3)

was introduced in [15]. Denoting the duals of these forms with lower indices, let us here also define a null frame of vectors ℓ , n, $m_{(i)}$ by

$$\ell = \frac{i}{\sqrt{2Q_m}}(e_{(m)} + ie_{(2m)}), \qquad n = -i\sqrt{\frac{Q_m}{2}}(e_{(m)} - ie_{(2m)}), \qquad (A.4)$$

with $m_{(i)}$ (i = 2, ..., n - 1) corresponding to $e_{(\mu)}$, $e_{(m+\mu)}$ $(\mu = 1, ..., m - 1$ from now on). One can show [15] that the null vectors ℓ , n are multiple WANDs of the type D metric (A.1) and that they are geodetic (and affinely parameterized). Both WANDs are complex in the coordinates used above, but note that they become in fact real in 'physical' coordinates since the metric (A.1) was obtained from a real Lorentzian metric by a Wick rotation with $x_m = ir$ in [16] and $Q_m < 0$ in the outer stationary region, where $\partial/\partial r$ is spacelike. Thus $\sqrt{Q_m} = i\sqrt{|Q_m|}$, so that reintroducing *r*, both vectors $ie_{(2m)}$ and $e_{(m)}$ become real $\left(e_{(m)}^{\alpha}(r) = i\delta^{\alpha m}\sqrt{Q_m}\right)$.

Let us now express the matrix L_{ij} (defined in section 2) in terms of Ricci rotation coefficients, which can be easily obtained from the connection 1-forms given in [15]:

$$L_{ij} = \ell_{a;b} m^a_{(i)} m^b_{(j)} = \frac{1}{\sqrt{2Q_m}} (e_{(m)a;b} + i e_{(2m)a;b}) m^a_{(i)} m^b_{(j)} = -\frac{1}{\sqrt{2Q_m}} (\gamma^m_{ij} + i \gamma^{2m}_{ij}), \quad (A.5)$$
with

with

$$\gamma^{m}_{\ \ \mu\mu} = \gamma^{m}_{\ \ m+\mu\ \ m+\mu} = -\frac{x_m \sqrt{Q_m}}{x_m^2 - x_\mu^2},\tag{A.6}$$

$$\gamma^{2m}_{\ m+\mu\ \mu} = -\gamma^{2m}_{\ \mu\ m+\mu} = -\frac{x_{\mu}\sqrt{Q_m}}{x_m^2 - x_{\mu}^2},\tag{A.7}$$

and with remaining Ricci rotation coefficients entering (A.5) being zero. Then,

$$S_{ij} = \frac{r}{\sqrt{2}} \begin{pmatrix} \delta_{\mu\nu} \frac{1}{r^2 + x_{\mu}^2} & 0\\ 0 & \delta_{\mu\nu} \frac{1}{r^2 + x_{\mu}^2} \end{pmatrix}, \qquad A_{ij} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -\delta_{\mu\nu} \frac{x_{\mu}}{r^2 + x_{\mu}^2}\\ \delta_{\mu\nu} \frac{x_{\mu}}{r^2 + x_{\mu}^2} & 0 \end{pmatrix}, \qquad (A.8)$$

where terms proportional to $\delta_{\mu\nu}$ symbolically represent an $(m-1) \times (m-1)$ diagonal block. Note that $S_{ij} \propto \delta_{ij}$ (that is, the shear is zero) iff n = 4. From this form of S_{ij} it follows that shear is non-zero for arbitrary even dimension n > 4 and expansion

$$S = \sqrt{2}r \sum_{\mu=1}^{m-1} \frac{1}{r^2 + x_{\mu}^2}$$
(A.9)

is non-zero in arbitrary even dimension $n \ge 4$. Note indeed that the WANDs ℓ and n are related by reflection symmetry, in agreement with the discussion in section 3. The twist is also obviously non-zero for any $n \ge 4$. Recall [16] finally that for n = 4 the metric (A.1) represents a subclass of the Plebański–Demiański family of type D spacetimes with two expanding, twisting and non-shearing principal null directions [1].

A.2. Odd dimensions, n = 2m + 1

In odd dimensions, in addition to (A.3) we define

$$e^{(2m+1)} = \sqrt{\tilde{S}} \left(\sum_{k=0}^{m} A^{(k)} \, \mathrm{d}\psi_k \right).$$
 (A.10)

Then, the null frame consists of ℓ , n given in (A.4), $m_{(i)}$ (i = 2, ..., n - 1) corresponding to $e_{(\mu)}$, $e_{(m+\mu)}$ ($\mu = 1, ..., m - 1$) and $e_{(2m+1)}$. Again, the null vectors ℓ and n are geodetic multiple WANDs of the type D metric (A.2) [15].

Now together with (A.7) we have

$$\gamma^{m}_{2m+1\ 2m+1} = -\frac{\sqrt{Q_{m}}}{x_{m}},\tag{A.11}$$

and thus

$$S_{ij} = \frac{1}{\sqrt{2}r} \begin{pmatrix} \delta_{\mu\nu} \frac{r^2}{r^2 + x_{\mu}^2} & 0 & 0\\ 0 & \delta_{\mu\nu} \frac{r^2}{r^2 + x_{\mu}^2} & 0\\ 0 & 0 & 1 \end{pmatrix}, \qquad A_{ij} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -\delta_{\mu\nu} \frac{x_{\mu}}{r^2 + x_{\mu}^2} & 0\\ \delta_{\mu\nu} \frac{x_{\mu}}{r^2 + x_{\mu}^2} & 0 & 0\\ 0 & 0 & 0 \end{pmatrix}.$$
(A.12)

Shear, expansion and twist are thus non-zero for arbitrary odd dimension n > 4.

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